

# Interactive / Steered Registration

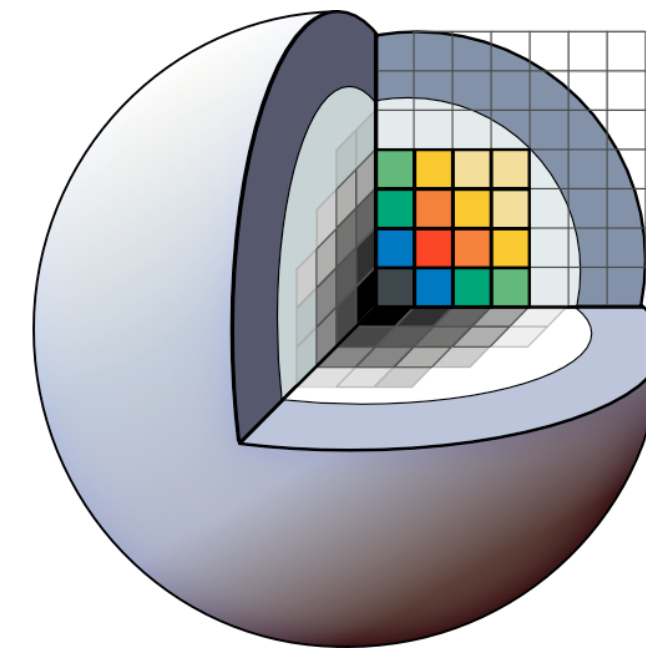
Steve Pieper

2nd Medical Image Registration Retreat

San Juan February 19, 2014

# Topics

- ◉ 3D Slicer Registration Technologies
  - Current Implementations and Architecture
- ◉ Steered Registration
  - Goals and Works in Progress
- ◉ Clinical Applications and Active Projects
  - Examples of Unsolved Registration Problems

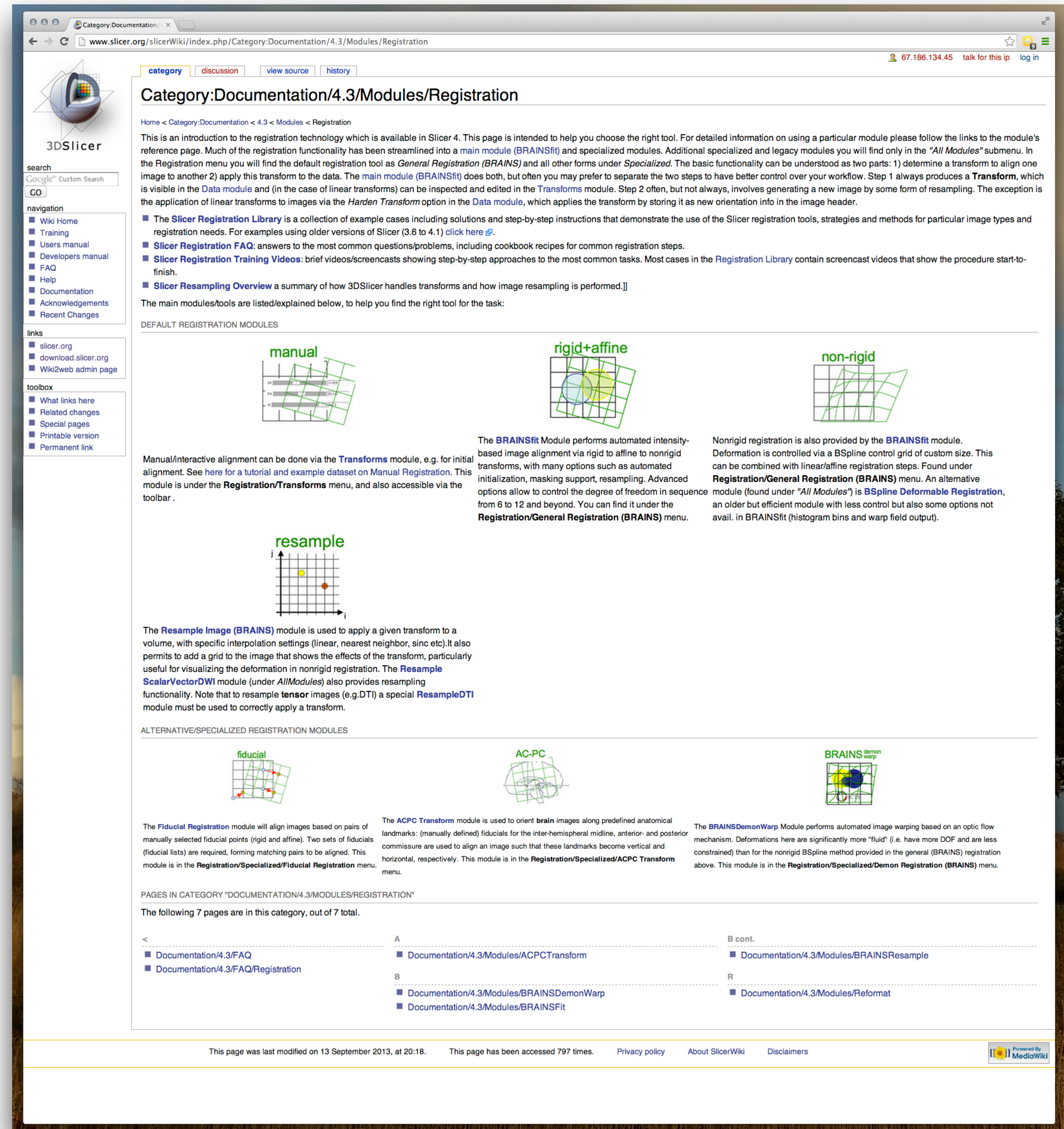




# 3D Slicer Registration Today

## REGISTRATION

- [Introduction to Registration \(Dominik Meier\)](#)
- [General Brainsfit Registration \(Hans Johnson\)](#)
- [Resample Image \(BRAINS\) \(Hans Johnson\)](#)
- [Specialized](#)
  - [ACPC Transform \(Nicole Aucoin\)](#)
  - [Demon Registration \(BRAINS\) \(Hans Johnson\)](#)
  - [Fiducial Registration \(Stephen Aylward\) !\[\]\(c8dce68b26731c7aa5915072fc9d68dd\_img.jpg\)](#)
  - [Vector Demon Registration \(Hans Johnson\)](#)
  - [Reformat \(Michael Jeulin-Lagarrigue\)](#)
  - [Segmentation Aided Registration \(Yi Gao\) !\[\]\(76b3245de86167eba9fcdc9cc9f32aa4\_img.jpg\)](#)



The screenshot shows the 3D Slicer Wiki page for Registration modules. The page is titled "Category:Documentation/4.3/Modules/Registration" and provides an introduction to the registration technology available in Slicer 4. It lists several registration modules and their descriptions:

- manual**: Manual/interactive alignment can be done via the **Transforms** module, e.g. for initial alignment. See here for a [tutorial](#) and [example dataset](#) on Manual Registration. This module is under the **Registration/Transforms** menu, and also accessible via the toolbar.
- rigid+affine**: The **BRAINSfit** Module performs automated intensity-based image alignment via rigid to affine to nonrigid transforms, with many options such as automated initialization, masking support, resampling. Advanced options allow to control the degree of freedom in sequence from 6 to 12 and beyond. You can find it under the **Registration/General Registration (BRAINS)** menu.
- non-rigid**: Nonrigid registration is also provided by the **BRAINSfit** module. Deformation is controlled via a BSpline control grid of custom size. This can be combined with linear/affine registration steps. Found under **Registration/General Registration (BRAINS)** menu. An alternative module (found under "All Modules") is **BSpline Deformable Registration**, an older but efficient module with less control but also some options not avail. in BRAINSfit (histogram bins and warp field output).
- resample**: The **Resample Image (BRAINS)** module is used to apply a given transform to a volume, with specific interpolation settings (linear, nearest neighbor, sinc etc). It also permits to add a grid to the image that shows the effects of the transform, particularly useful for visualizing the deformation in nonrigid registration. The **Resample ScalarVectorDWI** module (under *AllModules*) also provides resampling functionality. Note that to resample **tensor** images (e.g.DTI) a special **ResampleDTI** module must be used to correctly apply a transform.
- fiducial**: The **Fiducial Registration** module will align images based on pairs of manually selected fiducial points (rigid and affine). Two sets of fiducials (fiducial lists) are required, forming matching pairs to be aligned. This module is in the **Registration/Specialized/Fiducial Registration** menu.
- AC-PC**: The **ACPC Transform** module is used to orient **brain** images along predefined anatomical landmarks: (manually defined) fiducials for the inter-hemispheric midline, anterior- and posterior commissure are used to align an image such that these landmarks become vertical and horizontal, respectively. This module is in the **Registration/Specialized/ACPC Transform** menu.
- BRAINS demon warp**: The **BRAINSDemonWarp** Module performs automated image warping based on an optic flow mechanism. Deformations here are significantly more "fluid" (i.e. have more DOF and are less constrained) than for the nonrigid BSpline method provided in the general (BRAINS) registration above. This module is in the **Registration/Specialized/Demon Registration (BRAINS)** menu.

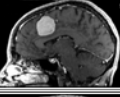
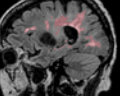
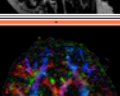
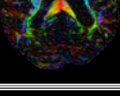
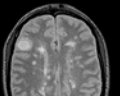
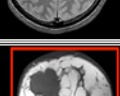

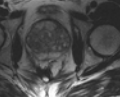
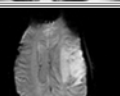

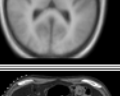
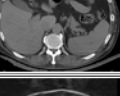
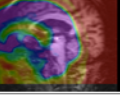
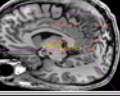

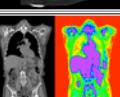
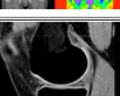
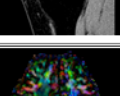
The page also includes a navigation sidebar, a search box, and a list of pages in the category "DOCUMENTATION/4.3/MODULES/REGISTRATION".

Special Thanks to Dominik Meier, BWH



# Registration Use Case Library

- 38 Worked Out Examples
  - Cross-Modality, Cross-Subject, Longitudinal...
  - Linear, Nonlinear
  - Scalars, Vectors, Tensors
  - Brain, Breast, Prostate, Knee...
- All Data Provided as .mrb Scene Files

ID	Description (click on image to access case page)	Structure	Type of Registration	Modality	Download
1	 Align baseline MRI of meningioma with follow-up.	brain tumor	rigid + affine	MRI	<a href="#">RegLib_C01.mrb</a> (input data only, Slicer mib file, 13 MB)
2	 Align MRI FLAIR with lesion segmentation to T1	multiple sclerosis	affine	MRI	<a href="#">RegLib_C02.mrb</a> (input data only, Slicer mib file, 19 MB) <a href="#">RegLib_C02_full.mrb</a> (input data + results, Slicer mib file, 19 MB)
3	 Align DTI volume with structural reference scan (T2)	brain tumor	affine + nonrigid	DTI	<a href="#">RegLib_C03.mrb</a> (input data only, Slicer mib file, 50 MB) <a href="#">RegLib_C03_full.mrb</a> (input data + results, Slicer mib file, 108 MB)
4	 Align both intra- and inter-exam MRI of a single subject.	multiple sclerosis	affine	MRI	<a href="#">RegLib_C04.mrb</a> (input data only, Slicer mib file, 19 MB) <a href="#">RegLib_C04_full.mrb</a> (input data + results, Slicer mib file, 19 MB)
6	 Align pre- and post-flx breast MRI	breast cancer	affine+nonrigid	MRI	<a href="#">RegLib_C06.mrb</a> (input data only, Slicer mib file, 40 MB) <a href="#">RegLib_C06_full.mrb</a> (input data + results, Slicer mib file, 65 MB)
7	 Align baseline and follow-up prostate MRI	prostate cancer	affine+nonrigid	MRI	<a href="#">RegLib_C07.mrb</a> (input data only, Slicer mib file, 8 MB) <a href="#">RegLib_C07_full.mrb</a> (input data + results, Slicer mib file, 27 MB)
9	 Align fMRI with structural MRI		rigid+nonrigid	MRI	<a href="#">RegLib_C09.mrb</a> (input data only, Slicer mib file, 40 MB) <a href="#">RegLib_C09_full.mrb</a> (input data + results, Slicer mib file, 162 MB)
10	 Align probabilistic group atlas with T1		rigid+nonrigid	MRI	<a href="#">RegLib_C10.mrb</a> (input data only, Slicer mib file, 12 MB) <a href="#">RegLib_C10_full.mrb</a> (input data + results, Slicer mib file, 50 MB)
12	 Align abdominal MRI with CT	liver tumor	affine + nonrigid	CT	<a href="#">RegLib_C12.mrb</a> (input data only, Slicer mib file, 35 MB) <a href="#">RegLib_C12_full.mrb</a> (input data + results, Slicer mib file, 68 MB)
14	 Align brain PET with lowres MRI	N/A	affine + nonrigid	CT	<a href="#">RegLib_C14.mrb</a> (input data only, Slicer mib file, 9 MB) <a href="#">RegLib_C14_full.mrb</a> (input data + results, Slicer mib file, 22 MB)
15	 AD/PC alignment of brain MRI	N/A	affine + nonrigid	CT	<a href="#">RegLib_C15.mrb</a> (input data only (incl. example fiducials), Slicer mib file, 22 MB) <a href="#">RegLib_C15_full.mrb</a> (input data + results, Slicer mib file, 22 MB)
17	 Preop MRI to intraop interventional CT	abdominal	affine	CT	<a href="#">RegLib_C17.mrb</a> (input data only (incl. example fiducials), Slicer mib file, 10 MB) <a href="#">RegLib_C17_full.mrb</a> (input data + results, Slicer mib file, 12 MB)
20	 Alignment of PET/CT follow-up to baseline	full body	rigid + affine + nonrigid	PET/CT	<a href="#">RegLib_C20.mrb</a> (input data only, Slicer mib file, 75 MB) <a href="#">RegLib_C20_full.mrb</a> (input data + results, Slicer mib file, 171 MB)
21	 Alignment of knee MRI (2 different subjects)	knee	rigid + affine + nonrigid	MRI	<a href="#">RegLib_C21.mrb</a> (input data + results, Slicer mib file, 12 MB)
27	 Alignment of DTI scan to structural reference T1-SPIGR for surgical planning (tumor resection)	brain tumor	affine + nonrigid	DTI	<a href="#">RegLib_C27.mrb</a> (input data, Slicer mib file 50MB) <a href="#">RegLib_C27_full.mrb</a> (input data + results, Slicer mib file 114MB)
29	 Alignment of DTI scan to structural reference T2/T1-SPIGR for surgical planning (tumor resection)	brain tumor	affine + nonrigid	DTI	<a href="#">RegLib_C29_raw.mrb</a> (input data, Slicer mib file, 71 MB) <a href="#">RegLib_C29_full.mrb</a> (input data+results, Slicer mib file, 124 MB)
32	 Alignment of structural reference T1 to a DTI scan		affine + nonrigid	DTI	<a href="#">RegLib_C32.mrb</a> (input data, Slicer mib file, 31 MB) <a href="#">RegLib_C32_full.mrb</a> (input data+results, Slicer mib file, 36 MB)
38	 Alignment of multi-sequence MRI	traumatic brain injury (TBI)	rigid	MRI	<a href="#">RegLib_C38.mrb</a> (input data, Slicer mib file, 42 MB)

# Registration Implementation

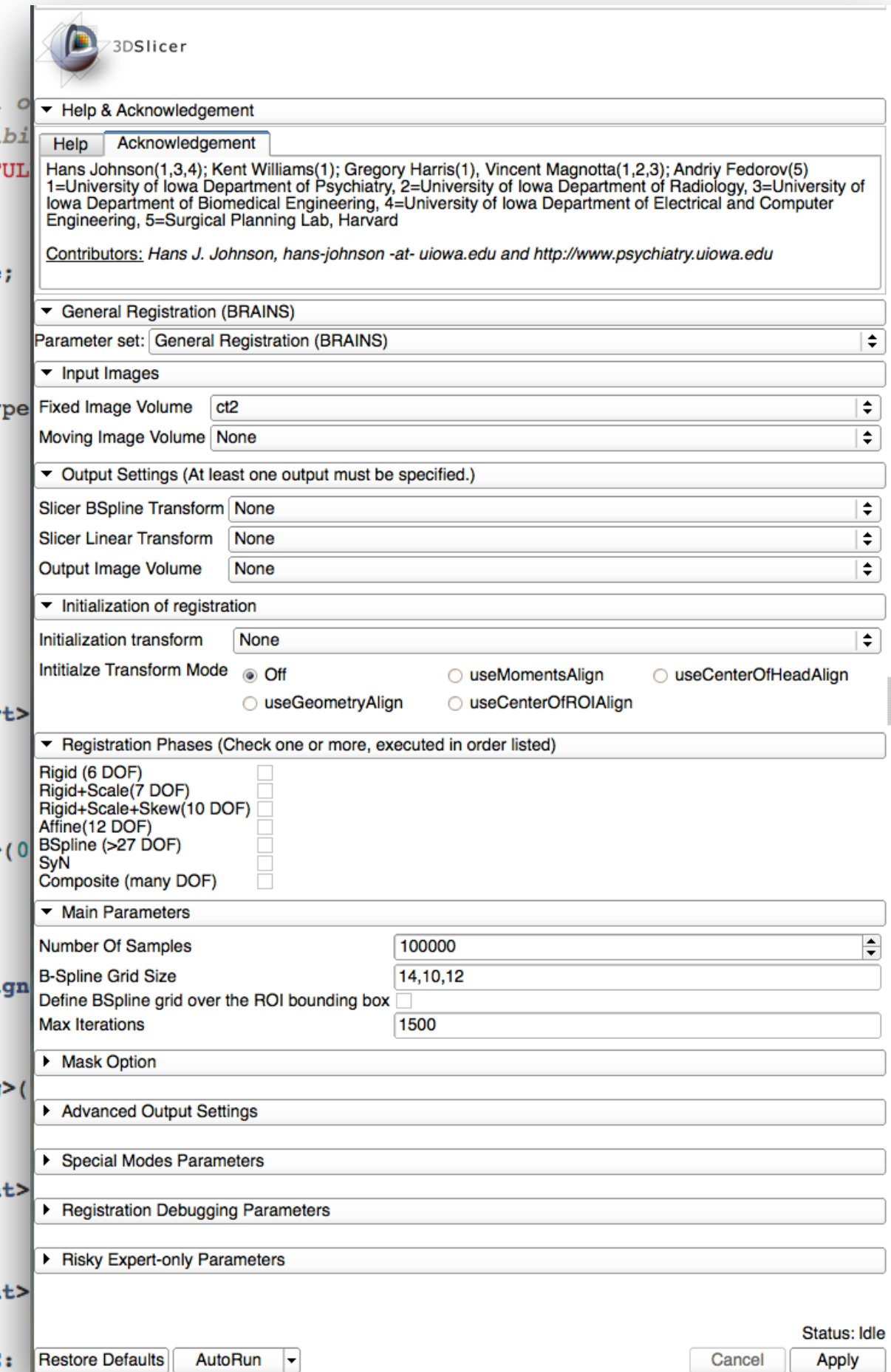
- Command Line Interface Modules (CLI)

- Written with “main(argc, argv)” style, but can be compiled to shared libraries with pointer access to image data
- Standardized argument syntax and automatic GUI generation
- “Pipeline” style autorun on changes to input data or parameters

- Leverages ITK

- 1.5 Million Lines of Code
- 14 Calendar Years
- 454 Years of Effort ([ohloh.net/p/itk](http://ohloh.net/p/itk))

```
766 int main( int argc, char * argv[] )
767 {
768
769     PARSE_ARGS;
770
771     // this line is here to be able to see the full o
772     // when the test succeeds (to see the reproducibi
773     std::cout << std::endl << "ctest needs: CTEST_FUL
774
775     itk::ImageIOBase::IOPixelType    pixelType;
776     itk::ImageIOBase::IOComponentType componentType;
777
778     try
779     {
780         itk::GetImageType(FixedImageFileName, pixelType
781
782         // This filter handles all types
783
784         switch( componentType )
785         {
786             case itk::ImageIOBase::CHAR:
787             case itk::ImageIOBase::UCHAR:
788             case itk::ImageIOBase::SHORT:
789                 return DoIt( argc, argv, static_cast<short>
790                 break;
791             case itk::ImageIOBase::USHORT:
792             case itk::ImageIOBase::INT:
793                 return DoIt( argc, argv, static_cast<int>(0
794                 break;
795             case itk::ImageIOBase::UINT:
796             case itk::ImageIOBase::ULONG:
797                 return DoIt( argc, argv, static_cast<unsigned
798                 break;
799             case itk::ImageIOBase::LONG:
800                 return DoIt( argc, argv, static_cast<long>(
801                 break;
802             case itk::ImageIOBase::FLOAT:
803                 return DoIt( argc, argv, static_cast<float>
804                 break;
805             case itk::ImageIOBase::DOUBLE:
806                 return DoIt( argc, argv, static_cast<float>
807                 break;
808             case itk::ImageIOBase::UNKNOWNCOMPONENTTYPE:
809             default:
810                 std::cout << "unknown component type" << std::endl;
811                 break;
812         }
813     }
814     catch( itk::ExceptionObject & excep )
815     {
816         std::cerr << argv[0] << ": exception caught !" << std::endl;
817         std::cerr << excep << std::endl;
818         return EXIT_FAILURE;
819     }
820     return EXIT_SUCCESS;
821 }
```





# Common Toolkit CTK

- Multinational Team of Likeminded Developers
  - DICOM, Visualization, IGT, Software Engineering...
  - Decades of Experience in Package Development
  - Multiyear History of Collaborative Development
- CTK has Adopted Slicer CLIs for Interoperability

The screenshot displays the 'The Team' page of the Common Toolkit (CTK) website. The page is structured as follows:

- Navigation:** Includes links for Main page, Community portal, Current events, Recent changes, Random page, and Help.
- Search:** A search bar with a 'Go' button.
- Toolbox:** Includes links for What links here, Related changes, Special pages, Printable version, and Permanent link.
- Contents (hide):** A table of contents listing: 1 Founders, 2 Supporting institutions, 3 Individual contributors, 4 Projects contributing to CTK, and 5 Grants, Fundings and Sponsors.
- Founders:** A list of individuals and their affiliations, including Hans-Peter Meinzer (German Cancer Research Center, Heidelberg, Germany), Marco Nolden (German Cancer Research Center, Heidelberg, Germany), Ron Kikinis (Harvard Medical School, Boston, MA, USA), Ivo Wolf (Mannheim University of Applied Sciences, Mannheim, Germany), Steve Pieper (Isomics, Cambridge, MA, USA), Stephen Aylward (Kitware Inc., Carboro, NC, USA), Julien Finet (Kitware Inc.), Jean-Christophe Fillon-Robin (Kitware Inc.), Julien Jomier (Kitware Inc.), Will Schroeder (Kitware Inc., Clifton Park, NY, USA), Kevin Cleary (Georgetown University, Washington DC, USA), Patrick Cheng (Georgetown University, Washington DC, USA), Ziv Yaniv (Georgetown University, Washington DC, USA), Lawrence Tarbox (Mallinckrodt Institute of Radiology, St. Louis, MO, USA), Marco Viceconti (Laboratorio di Teologia Medica, Bologna, Italy), Daniele Giunchi (SCS - BSC, Bologna Italy), Paolo Quadroni (SCS - BSC, Bologna Italy), Michael Orken (OFFIS DICOM Team, Oldenburg, Germany), Nicholas Ayache (Sophia Antipolis, Inria, France), Olivier Clatz (Sophia Antipolis, Inria, France), Maxime Sermesant (Sophia Antipolis, Inria, France), Pierni Filardi (Sophia Antipolis, Inria, France), Gianluca Paladini (Siemens Corporate Research, Princeton, NJ, USA), and David Clunie (RadPharm, Princeton, NJ, USA).
- Supporting institutions:** A grid of logos and names for various institutions, including dktz, Kitware, Inria, Isomics, Inc., Hochschule Mannheim, DICOM@OFFIS, RADPHARM, SIEMENS corporate research, SPI Surgical Planning Laboratory, UCL, UNIVERSITAT POMPEU FABRA, Washington University in St. Louis, and The University of Sheffield.
- Individual contributors:** A list of names including Jean-Christophe Fillon-Robin, Julien Finet, Sascha Zeltzer, Steve Pieper, Marco Nolden, Nicholas Herfambang (inactive), Matt Clarkson, Benjamin Long, Ivo Wolf, Michael Orken, Danielle Pace, and Nicolas Rannou.
- Projects contributing to CTK:** A grid of logos for 3D Slicer, GIMIAS, maf3, medInria, MITK, and ParaView.
- Grants, Fundings and Sponsors:** A list of funding sources, including Air Force Research Laboratories under Phases I and II of the SBIR contract "Generating Labeled Voxels for Numerical Simulation", AFRA supplement # to NAC, Surgery (Cognition Guided Surgery, SFB/Transregio 125), National Alliance for Medical Image Computing, NeuroImage Analysis Center, and Virtual Physiological Human Network of Excellence.

The footer of the page indicates that the page was last modified on 5 September 2013 at 12:17 and has been accessed 9,369 times. It also includes links for Privacy policy, About Commonk, and Disclaimers.



# CTK

The image displays the CTK (Cortical Toolbox) interface, which is used for medical image registration. The main window shows a 2D/3D scene view with four brain slices. The top-left corner shows the 'GIMIAS' logo and menu. The top-right corner shows the 'Data tree' with the following structure:

```
Root
├── source_2down
├── RegAladin (NiftyReg)_outputWarpedImageName
└── target_2down
```

The 'RegAladin (NiftyReg)' control panel on the right shows the following parameters:

- Reference image:  1#source\_2down (Volume image, -)
- Floating image:  4#target\_2down (Volume image, -)
- Ref. mask:  1#source\_2down (Volume image, -)
- Flo. mask:  1#source\_2down (Volume image, -)

The bottom status bar displays the following information:

Position: <2.00, 0.00, -2.00> mm; Index: <23, 27, 22>; Time: 0.00 ms; Pixelvalue: 56.00 129.07 MB (6.52 %)



# BRAINSFit

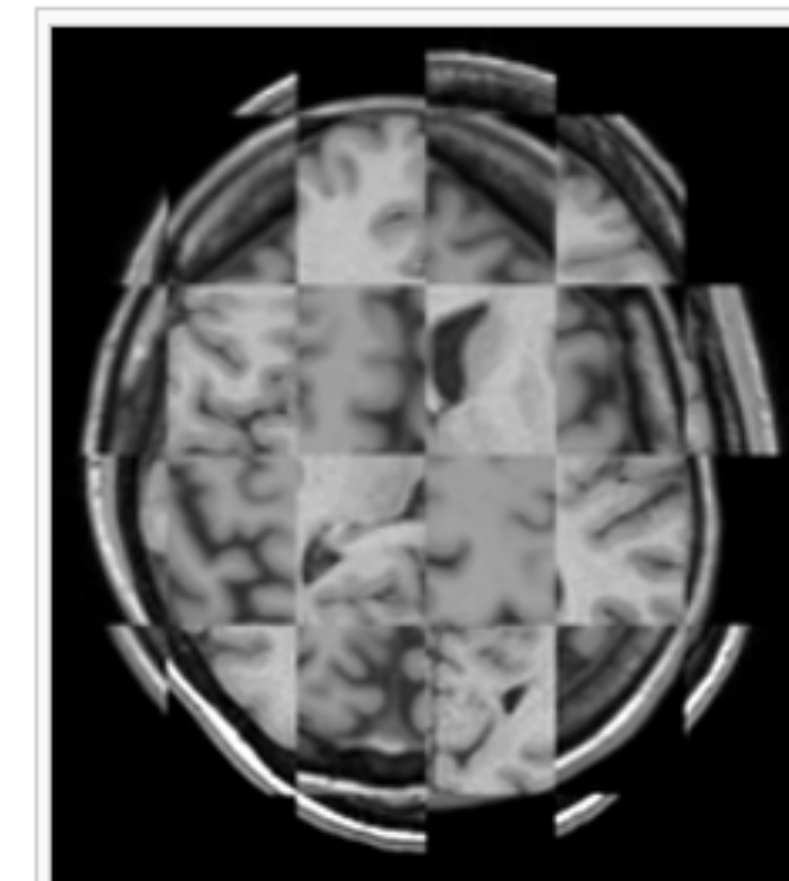


THE UNIVERSITY  
OF IOWA

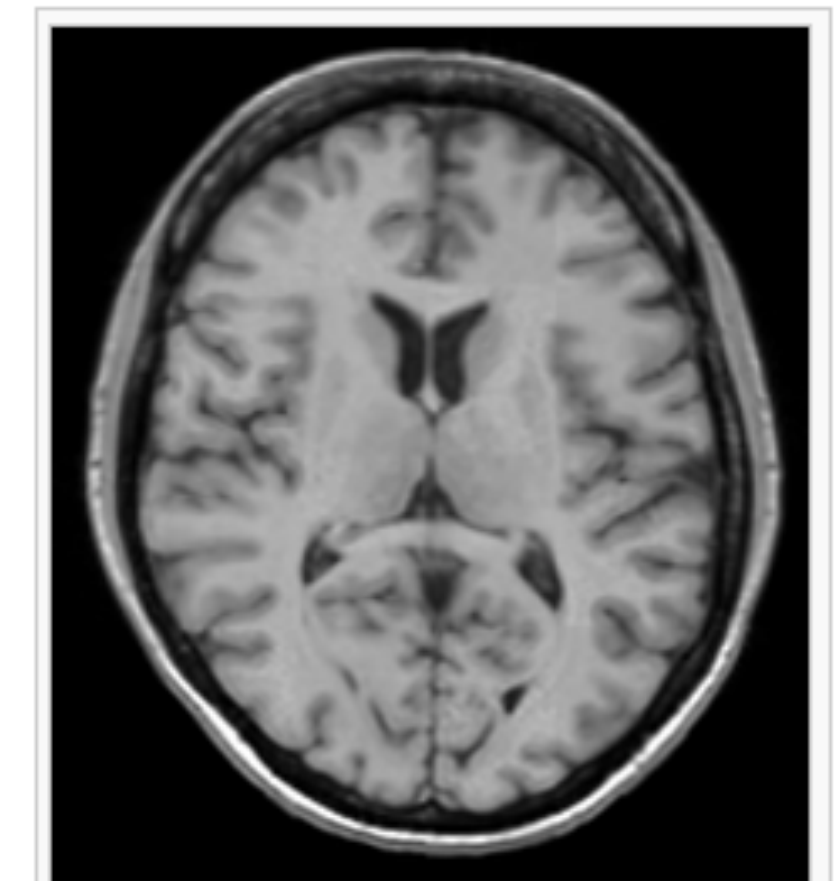


- De Facto Standard Slicer Registration CLI
  - Initializations: Transform, CenterOfHead, CenterOfROI, Moments, Geometry, Histogram Match
  - Transforms: Rigid, ScaleVersor, ScaleSkewVersor, Affine, BSpline, Symmetric Diffeomorphic (SyN), Composite
  - Dozens of Other Parameters
    - Normal Ones
    - Risky Ones
- Uses Range from Psychiatry to Prostate Biopsy

```
BRAINSFit --fixedVolume test.nii.gz \  
--movingVolume test2.nii.gz \  
--outputVolume testT1LongRegFixed.nii.gz \  
--outputTransform longToBase.xform \  
--transformType Rigid \  
--histogramMatch \  
--initializeTransformMode useCenterOfHeadAlign \  
--maskProcessingMode ROIAUTO \  
--ROIAutoDilateSize 3 \  
--interpolationMode Linear
```



Longitudinal Checkerboard  
Before registration



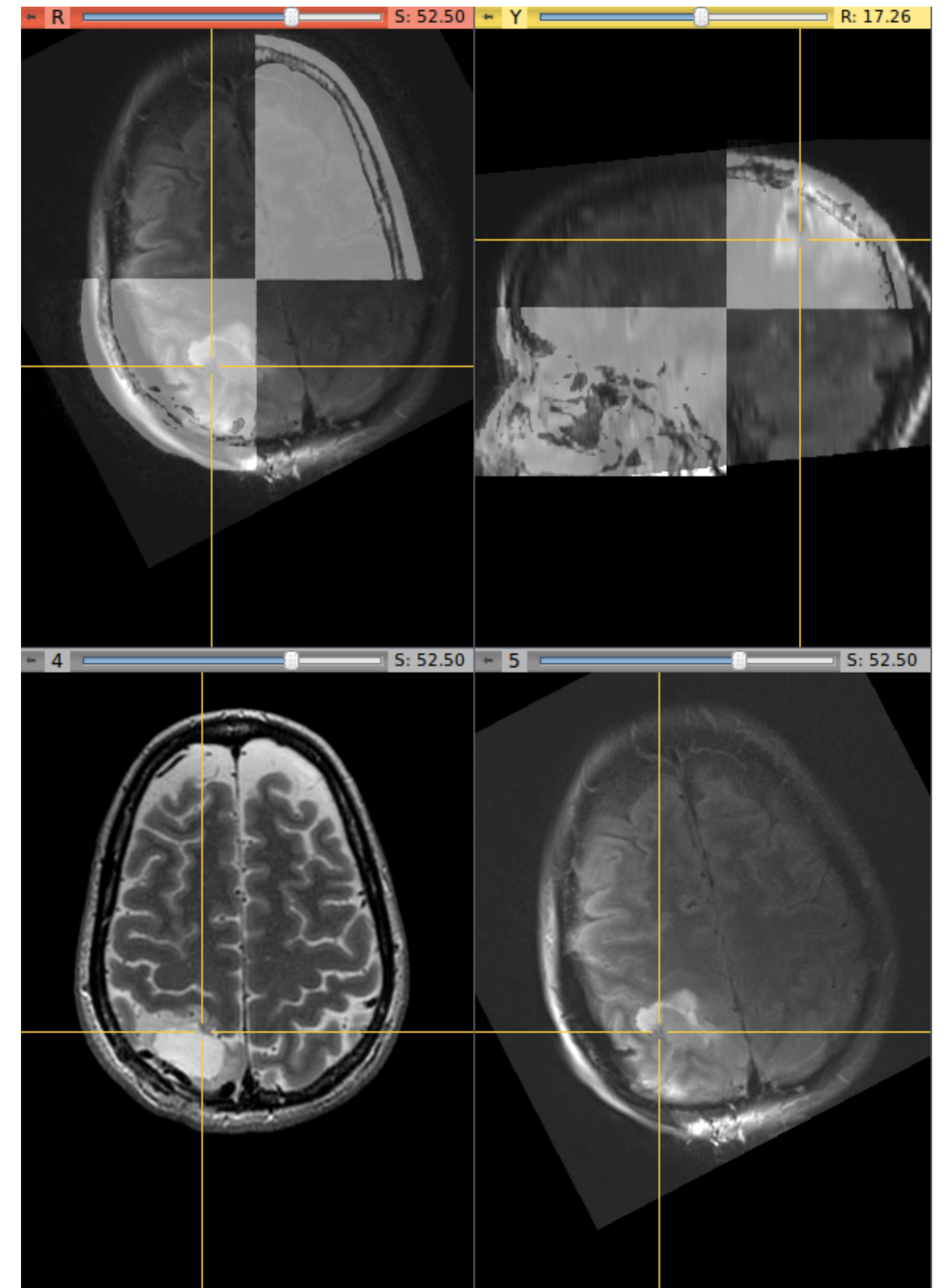
Longitudinal Checkerboard  
After registration

So What's Wrong with  
Registration Algorithms?

# So What's Wrong with Registration Algorithms?

- Algorithms Don't Understand the Images
  - What to ignore
  - How the images were obtained
  - What was imaged
- Too Slow
  - Should be essentially instantaneous
- Hard to Tell if the Answer is Right
  - Requires visual inspection
- Too Many Parameters
  - Parameters are the last refuge of an algorithm developer\*
  - If the answer is wrong, which parameter to change?

\* Apologies to Samuel Johnson

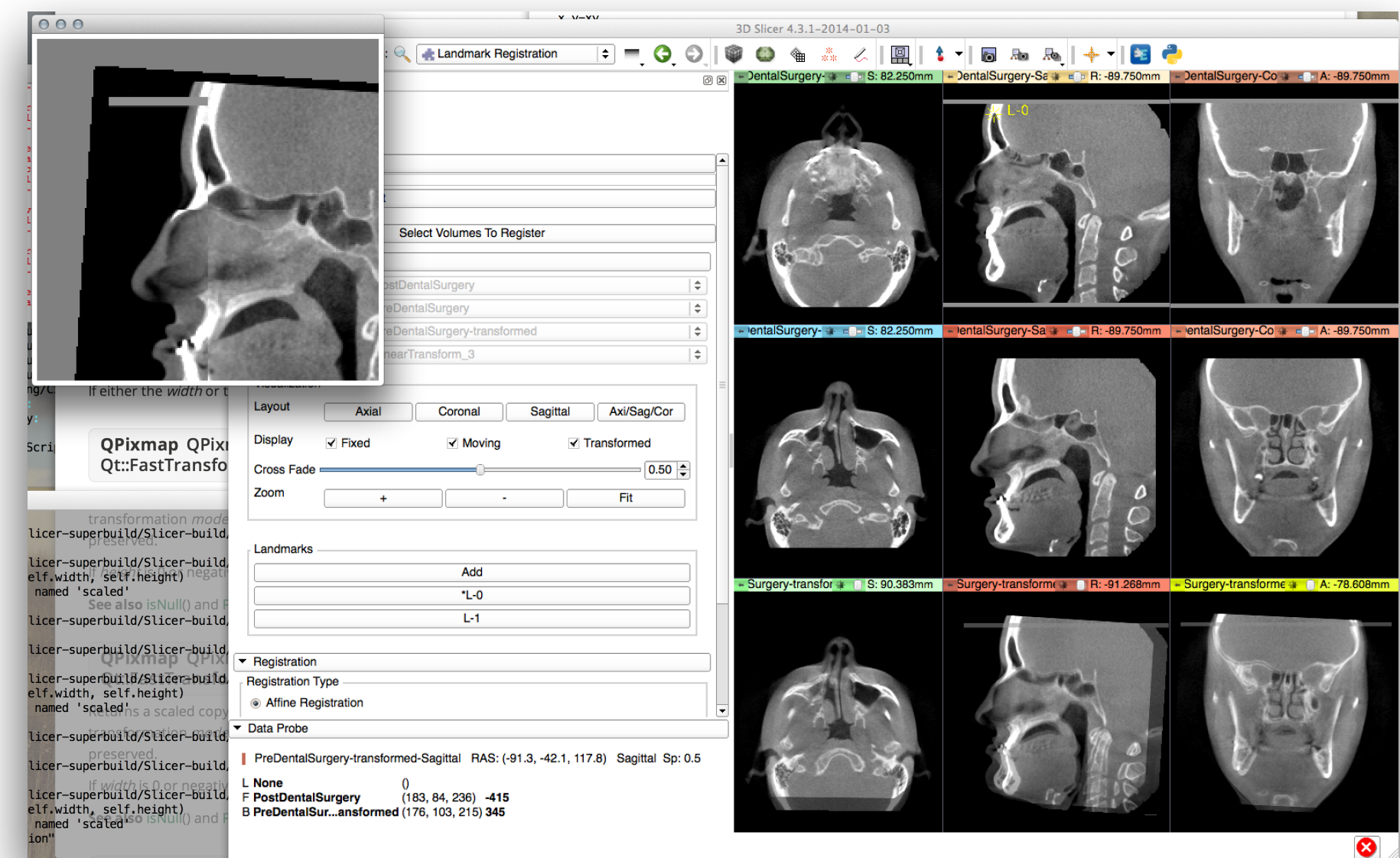


Preprocedure MR (bottom left) and intra-procedure MR (bottom right) after rigid registration. Data Courtesy Dr. Alexandra Golby.



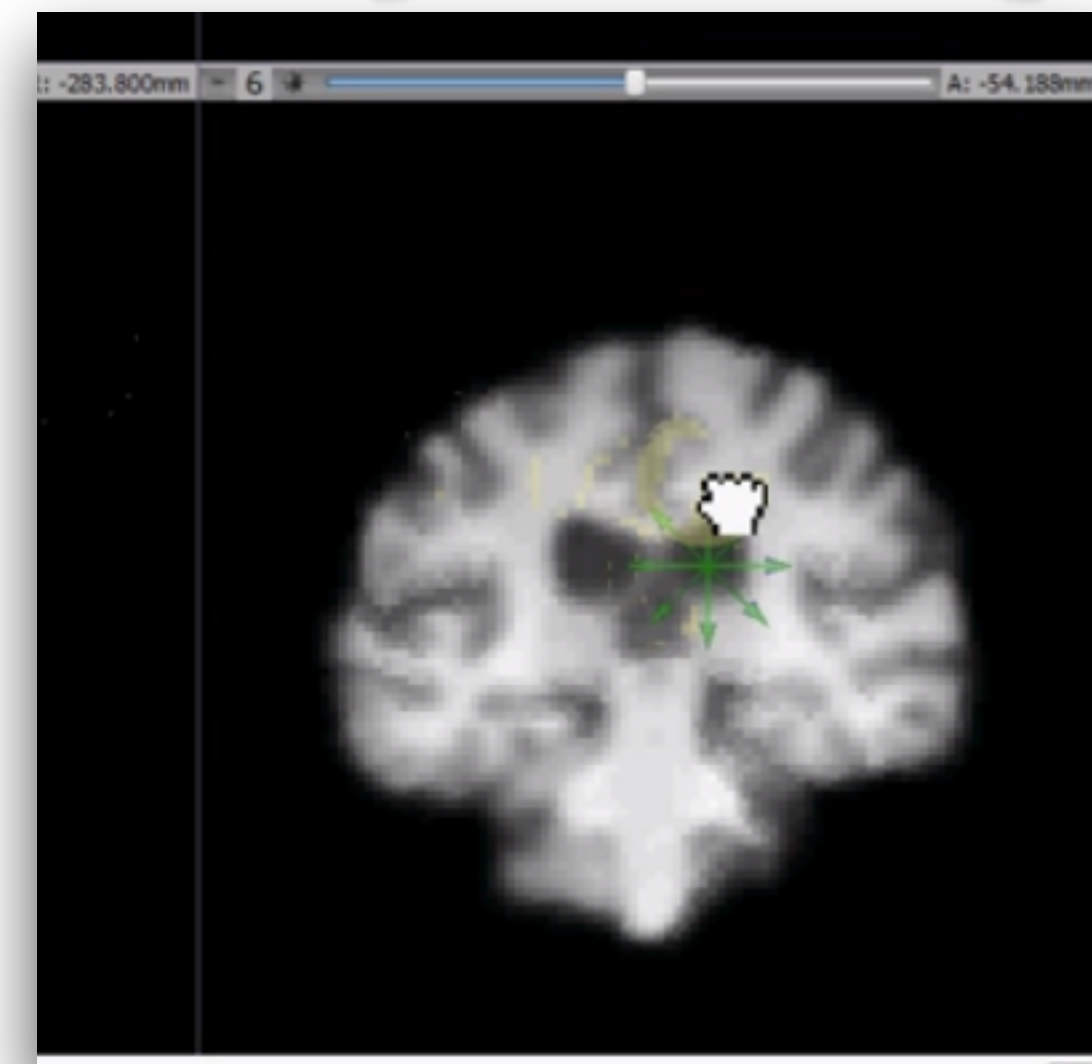
# What can be done?

- Reach in and Grab It!
  - Tell the algorithm what parts should line up
  - Tell it what to ignore
  - Pin down the parts that are right and let the algorithm figure out the rest
- Fast Detailed Inspection Tools
  - Need to review anyway, so fix it at the same time
  - See the 3D deformation
- Learn from the Fixes
  - Use manual corrections to adjust parameters
  - “Task Level Control”
- Goal: Integrate the Parameter Setting and Quality Assurance Review Steps into the Algorithm Itself

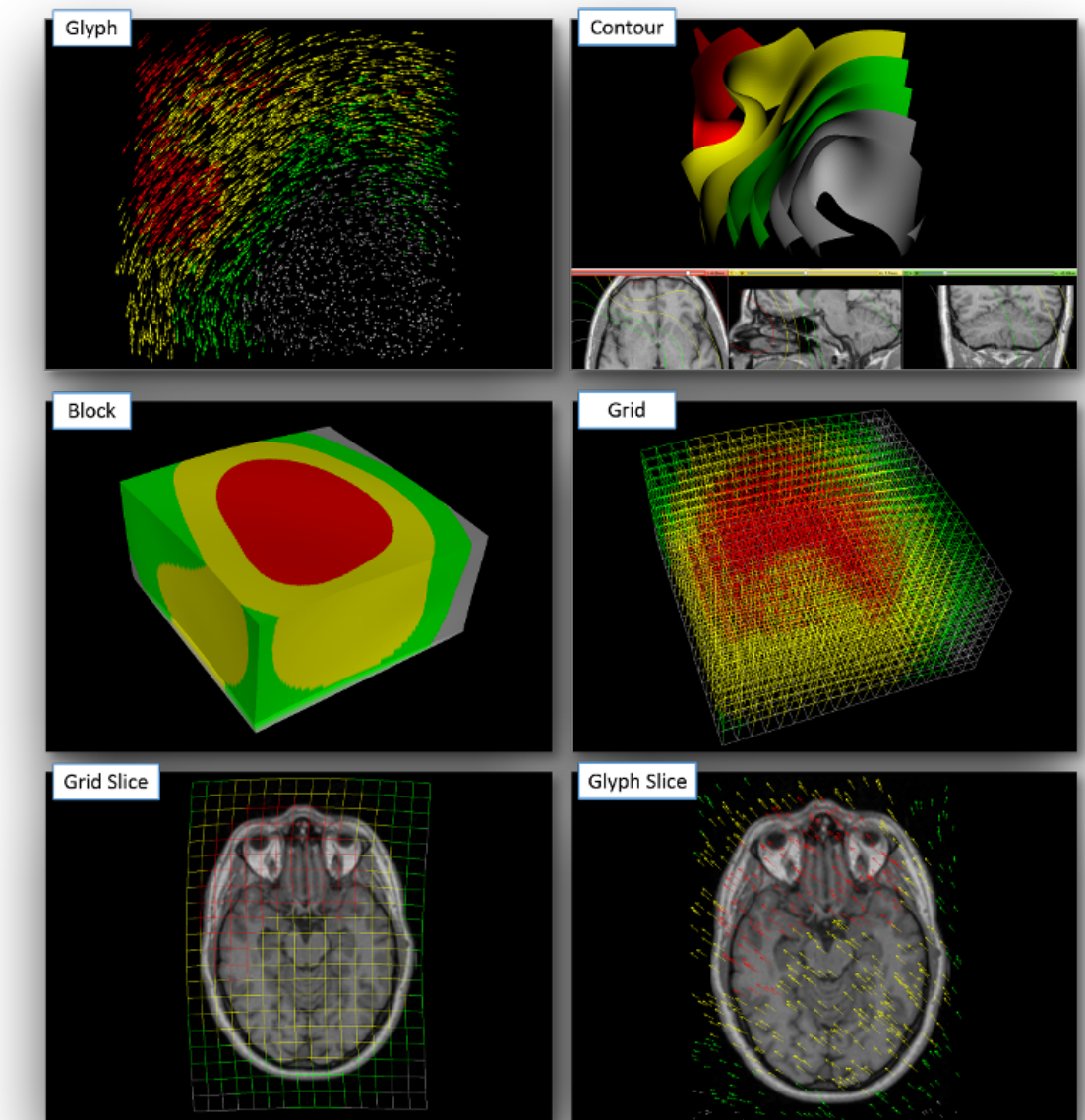


Work in Progress

Landmark Registration: Pieper



Registration Gestures: Prastawa, Miller



Transform Visualizer: King, SlicerRT

# What can be done?

Visualization

Control

Automation



# Steered Registration Goals

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## Visualization

- ◉ Data Fusion Tools
  - Color, Overlays, Crossfades, Animations
  - Interactive Inspection
- ◉ 3D Slice Plane Visualization
- ◉ Volume Rendering
  - Multiple Volume
  - Incorporating Nonlinear Transforms
  - Real Time
  - Interactive Data Fusion

## Control

- ◉ Precise Placement
  - Reviewable
  - Editable
  - Undo/Redoable
- ◉ Native 3D Control
  - Optimal use of human eye hand coordination and spatial skills
  - Hand tracking, haptics...
- ◉ More than Just Points
  - Local Orientation
  - Surface Matching

## Automation

- ◉ Simplify Input
  - Interpret control in terms of current transformation
  - Snap to right answer
  - Extrapolate input (“zipper”)
- ◉ Learn from Input
  - Adjust optimization metrics based on user input so far
  - Learn from previous QC data
- ◉ Expose (Un)certainty
  - Identify local minima as needing QC



**What is being done?**

# Software Support for Steered Registration

## ● VTK

- PRO: Rich set of transform types closely integrated with visualization pipelines and vtkImageReslice
- PRO: Very interactive by design
- CON: No nonlinear transforms in volume rendering

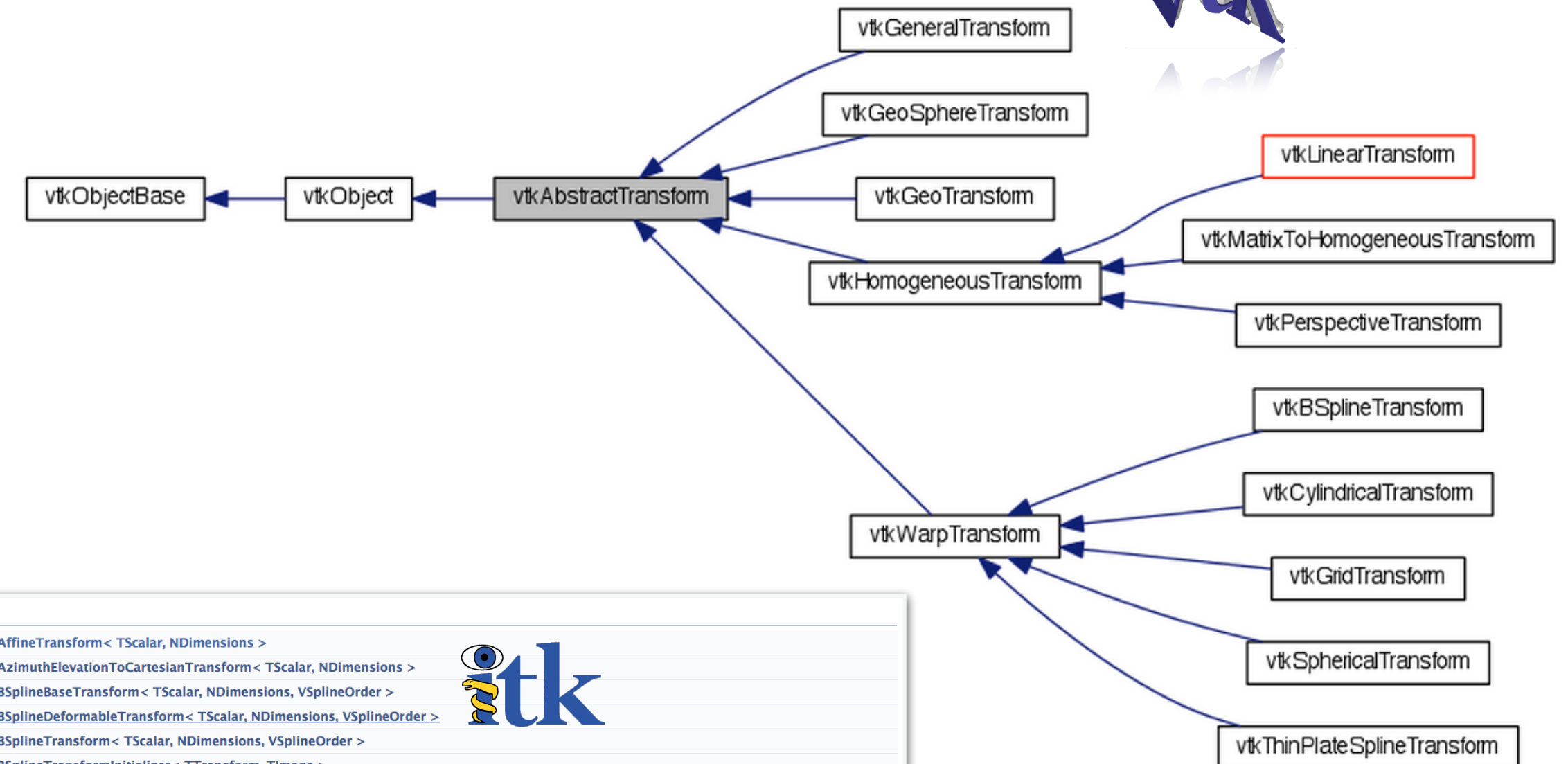
## ● ITK

- PRO: Rich set of algorithms
- CON: Optimizers not set up for interaction

## ● vtkITK

- PRO: Provides glue to expose ITK classes in VTK Pipelines
- CON: Complex and imperfect match of pipelines

#include <vtkAbstractTransform.h>  
Inheritance diagram for vtkAbstractTransform:



```
Classes
class itk::AffineTransform < TScalar, NDimensions >
class itk::AzimuthElevationToCartesianTransform < TScalar, NDimensions >
class itk::BSplineBaseTransform < TScalar, NDimensions, VSplineOrder >
class itk::BSplineDeformableTransform < TScalar, NDimensions, VSplineOrder >
class itk::BSplineTransform < TScalar, NDimensions, VSplineOrder >
class itk::BSplineTransformInitializer < TTransform, TImage >
class itk::CenteredAffineTransform < TScalar, NDimensions >
class itk::CenteredEuler3DTransform < TScalar >
class itk::CenteredRigid2DTransform < TScalar >
class itk::CenteredSimilarity2DTransform < TScalar >
class itk::CenteredTransformInitializer < TTransform, TFixedImage, TMovingImage >
class itk::CenteredVersorTransformInitializer < TFixedImage, TMovingImage >
class itk::CompositeTransform < TScalar, NDimensions >
class itk::ElasticBodyReciprocalSplineKernelTransform < TScalar, NDimensions >
class itk::ElasticBodySplineKernelTransform < TScalar, NDimensions >
class itk::Euler2DTransform < TScalar >
class itk::Euler3DTransform < TScalar >
class itk::FixedCenterOfRotationAffineTransform < TScalar, NDimensions >
class itk::IdentityTransform < TScalar, NDimensions >
class itkTransformBaseTemplate
class itk::KernelTransform < TScalar, NDimensions >
class itk::LandmarkBasedTransformInitializer < TTransform, TFixedImage, TMovingImage >
class itk::MatrixOffsetTransformBase < TScalar, NInputDimensions, NOutputDimensions >
class itk::MultiTransform < TScalar, NDimensions, NSubDimensions >
class itk::QuaternionRigidTransform < TScalar >
class itk::Rigid2DTransform < TScalar >
class itk::Rigid3DPerspectiveTransform < TScalar >
class itk::Rigid3DTransform < TScalar >
class itk::ScalableAffineTransform < TScalar, NDimensions >
class itk::ScaleLogarithmicTransform < TScalar, NDimensions >
class itk::ScaleSkewVersor3DTransform < TScalar >
class itk::ScaleTransform < TScalar, NDimensions >
class itk::ScaleVersor3DTransform < TScalar >
class itk::Similarity2DTransform < TScalar >
class itk::Similarity3DTransform < TScalar >
class itk::ThinPlateR2LogRSPplineKernelTransform < TScalar, NDimensions >
class itk::ThinPlateSplineKernelTransform < TScalar, NDimensions >
class itk::Transform < TScalar, NInputDimensions, NOutputDimensions >
class itk::TranslationTransform < TScalar, NDimensions >
class itk::VersorRigid3DTransform < TScalar >
class itk::VersorTransform < TScalar >
class itk::VolumeSplineKernelTransform < TScalar, NDimensions >
```



```
Public Member Functions
void DeepCopy (vtkITKBSplineTransform *xform)
copy underlying ITK transform
BulkTransformType const * GetBulkTransform () const
void GetBulkTransform (double linear[3][3], double offset[3])
const double * GetFixedParameters () const
Return a pointer to the fixed parameter array.
void GetGridOrigin (double *origin) const
void GetGridSize (unsigned int *size) const
void GetGridSpacing (double *spacing) const
itk::Transform < double, 3, 3 >
::Pointer GetITKTransform () const
unsigned int GetNumberOfFixedParameters () const
The number of fixed parameters.
unsigned int GetNumberOfParameters () const
The number of elements in the parameter vector.
const double * GetParameters () const
unsigned int GetSplineOrder () const
bool GetSwitchCoordinateSystem () const
vtkAbstractTransform * MakeTransform ()
virtual void PrintSelf (ostream &os, vtkIndent indent)
void SetBulkTransform (const double linear[3][3], const double offset[3])
BulkTransform should be in the ITK coordinate system, which is LPS.
void SetFixedParameters (const double *param, unsigned N)
Set the fixed parameters.
void SetGridOrigin (const double origin[3])
void SetGridSize (const unsigned int size[3])
Number of grid nodes in each dimension.
void SetGridSpacing (const double spacing[3])
The spacing between grid nodes.
void SetParameters (const double *param)
Set the BSpline parameters.
void SetParameters (vtkDoubleArray &param)
See the documentation of SetParameters(double[]).
void SetSplineOrder (unsigned int)
SetOrder MUST be called first before other set functions.
void SetSwitchCoordinateSystem (bool v)
Sets whether a LPS->RAS conversion should be done.
vtkTypeRevisionMacro (vtkITKBSplineTransform, vtkWarpTransform)

Static Public Member Functions
static vtkITKBSplineTransform * New ()

Public Attributes
vtkITKBSplineTransformHelper * Helper

Protected Member Functions
void ForwardTransformDerivative (const float in[3], float out[3], float derivative[3][3])
void ForwardTransformDerivative (const double in[3], double out[3], double derivative[3][3])
void ForwardTransformPoint (const float in[3], float out[3])
void ForwardTransformPoint (const double in[3], double out[3])
void InverseTransformDerivative (const float in[3], float out[3], float derivative[3][3])
void InverseTransformDerivative (const double in[3], double out[3], double derivative[3][3])
void InverseTransformPoint (const double in[3], double out[3])
void InverseTransformPoint (const float in[3], float out[3])
virtual ~vtkITKBSplineTransform ()
```

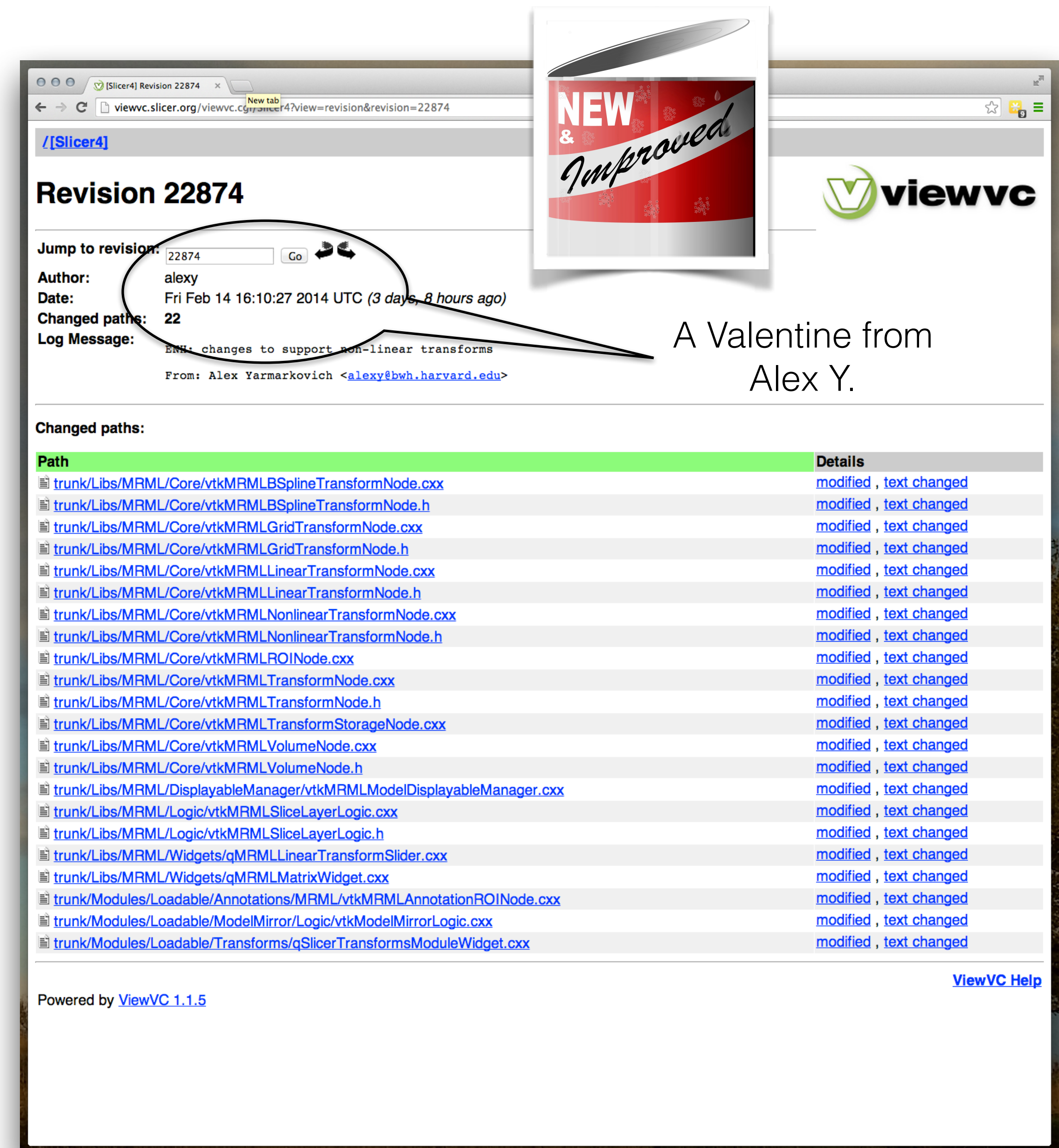






# Nonlinear Transforms

- Slicer Nightly Builds Support Live Nonlinear Transforms
  - Drag-and-Drop Transformable Nodes
    - Volumes, Models, Fiducials...
  - Slice Pipeline Applies Nonlinear Transform on Visible Slice
  - TransformToParent and TransformFromParent Calculated as Needed and Cached
  - CLIs Output or Programatic Modifications Update on the Fly
- TODO: Documentation, Nonlinear Transforms Module GUI, Further Testing...



**Revision 22874**

Jump to revision:  Go

Author: alexy  
Date: Fri Feb 14 16:10:27 2014 UTC (3 days, 8 hours ago)  
Changed paths: 22  
Log Message: ENH: changes to support non-linear transforms  
From: Alex Yarmarkovich <[alex@bwh.harvard.edu](mailto:alex@bwh.harvard.edu)>

Changed paths:

Path	Details
<a href="#">trunk/Libs/MRML/Core/vtkMRMLBSplineTransformNode.cxx</a>	modified, text changed
<a href="#">trunk/Libs/MRML/Core/vtkMRMLBSplineTransformNode.h</a>	modified, text changed
<a href="#">trunk/Libs/MRML/Core/vtkMRMLGridTransformNode.cxx</a>	modified, text changed
<a href="#">trunk/Libs/MRML/Core/vtkMRMLGridTransformNode.h</a>	modified, text changed
<a href="#">trunk/Libs/MRML/Core/vtkMRMLLinearTransformNode.cxx</a>	modified, text changed
<a href="#">trunk/Libs/MRML/Core/vtkMRMLLinearTransformNode.h</a>	modified, text changed
<a href="#">trunk/Libs/MRML/Core/vtkMRMLNonlinearTransformNode.cxx</a>	modified, text changed
<a href="#">trunk/Libs/MRML/Core/vtkMRMLNonlinearTransformNode.h</a>	modified, text changed
<a href="#">trunk/Libs/MRML/Core/vtkMRMLROINode.cxx</a>	modified, text changed
<a href="#">trunk/Libs/MRML/Core/vtkMRMLTransformNode.cxx</a>	modified, text changed
<a href="#">trunk/Libs/MRML/Core/vtkMRMLTransformNode.h</a>	modified, text changed
<a href="#">trunk/Libs/MRML/Core/vtkMRMLTransformStorageNode.cxx</a>	modified, text changed
<a href="#">trunk/Libs/MRML/Core/vtkMRMLVolumeNode.cxx</a>	modified, text changed
<a href="#">trunk/Libs/MRML/Core/vtkMRMLVolumeNode.h</a>	modified, text changed
<a href="#">trunk/Libs/MRML/DisplayableManager/vtkMRMLModelDisplayableManager.cxx</a>	modified, text changed
<a href="#">trunk/Libs/MRML/Logic/vtkMRMLSliceLayerLogic.cxx</a>	modified, text changed
<a href="#">trunk/Libs/MRML/Logic/vtkMRMLSliceLayerLogic.h</a>	modified, text changed
<a href="#">trunk/Libs/MRML/Widgets/qMRMLLinearTransformSlider.cxx</a>	modified, text changed
<a href="#">trunk/Libs/MRML/Widgets/qMRMLMatrixWidget.cxx</a>	modified, text changed
<a href="#">trunk/Modules/Loadable/Annotations/MRML/vtkMRMLAnnotationROINode.cxx</a>	modified, text changed
<a href="#">trunk/Modules/Loadable/ModelMirror/Logic/vtkModelMirrorLogic.cxx</a>	modified, text changed
<a href="#">trunk/Modules/Loadable/Transforms/qSlicerTransformsModuleWidget.cxx</a>	modified, text changed

Powered by [ViewVC 1.1.5](#)

[ViewVC Help](#)

**NEW & Improved**

A Valentine from Alex Y.



# Landmark Registration and Registration Plugins

- LandmarkRegistration is Becoming a General Steered Registration Tool

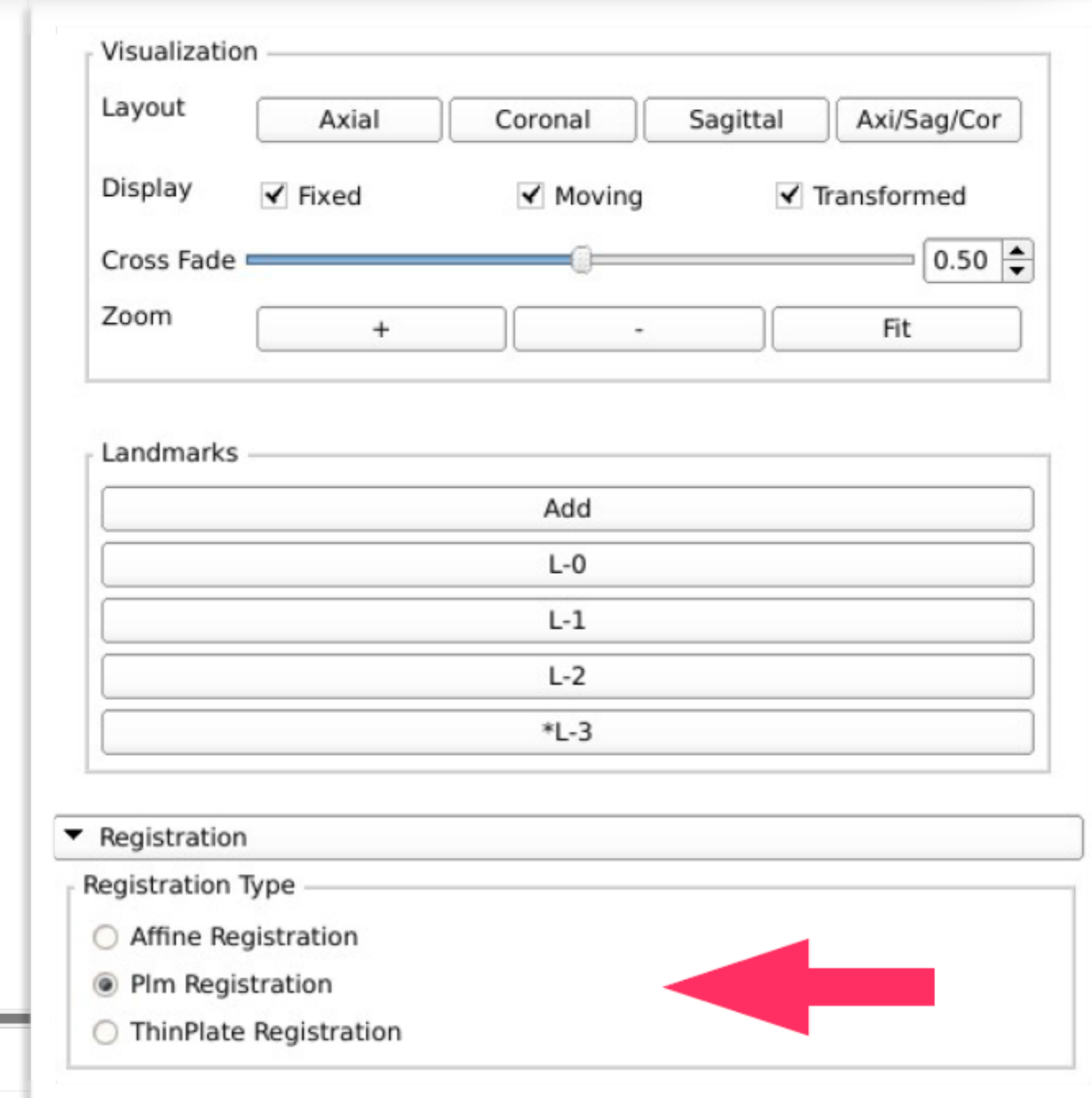
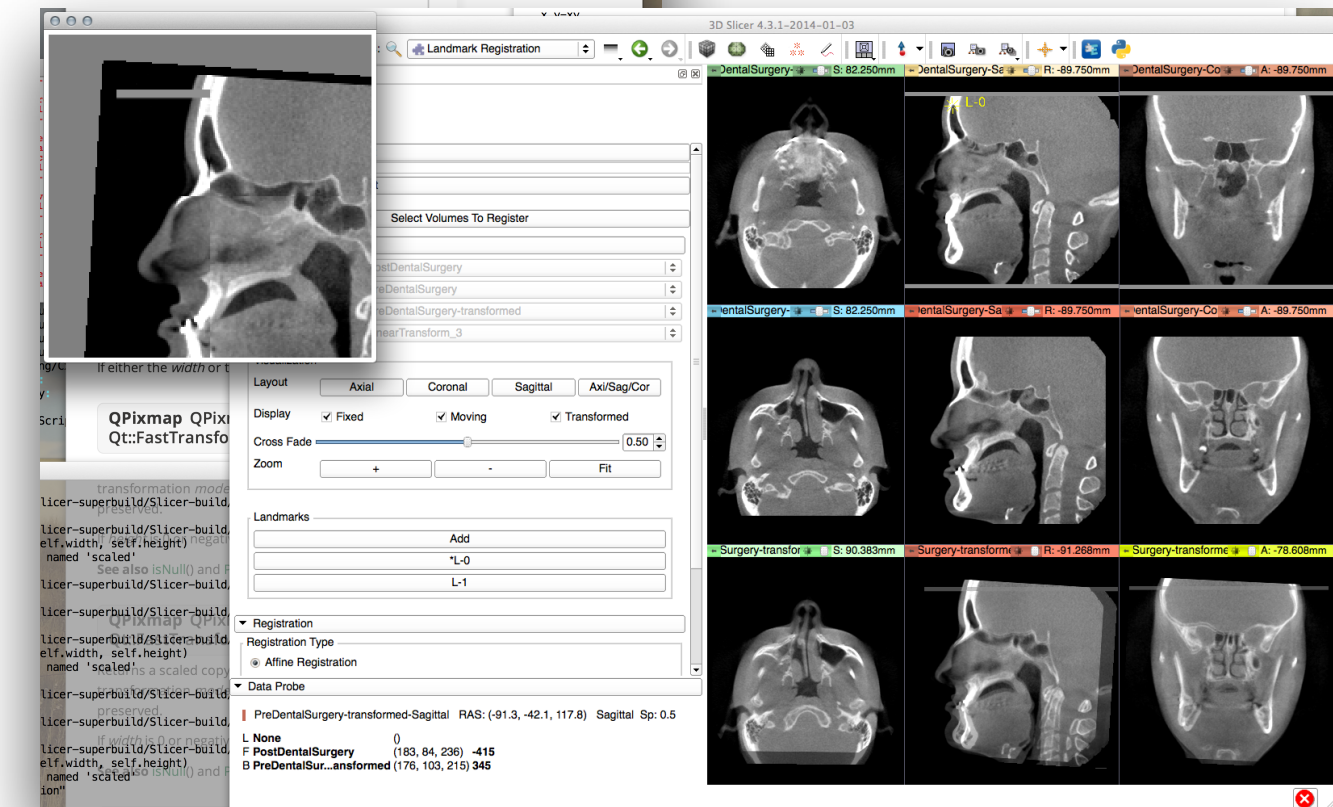
- Manages Fixed, Moving, and Transformed Volumes
- Manages Landmarks
  - Defined as matched Fiducials on Fixed and Moving
- Manages Visualization Modes
  - Viewer Per Volume, Cross Fade, Orientations

- Plugins Implement Steered Algorithms

- Update Transforms in Response to User Input
- Can call CLIs or loadable libraries

Work in Progress

```
1 import os
2 from __main__ import vtk, qt, ctk, slicer
3 import RegistrationLib
4
5 #####
6 #
7 #
8 #
9 comment = """
10
11 RegistrationPlugin is a superclass for code that plugs into the
12 slicer LandmarkRegistration module.
13
14 These classes are Abstract.
15
16 # TODO :
17 """
18 #####
19
20 # RegistrationPlugin
21
22 class RegistrationPlugin(object):
23     """ Base class for Registration plugins
24     """
25
26     # generic settings that can (should) be overridden by the subclass
27
28     # displayed for the user to select the registration
29     name = "Generic Registration"
30     tooltip = "No additional information available"
31
32     # can be true or false
33     # - True: landmarks are displayed and managed by LandmarkRegistration
34     # - False: landmarks are hidden
35     useLandmarks = True
36
37     # can be any non-negative number
38     # - widget will be disabled until landmarks are defined
39     landmarksNeededToEnable = 1
40
41     # used for reloading - every concrete class should include this
42     sourceFile = __file__
43
44     def __init__(self, parent=None):
45
46         # state variables for all plugins and subclasses
47         self.parent = parent
48         self.observerTags = []
49         self.widgets = []
50
51     def create(self, registrationState):
52         """Call this method from your subclass to manage dynamic layout
53         and widget deleting
54         - registrationState is a callable object that will give you an instance
55         of a RegistrationState object that you can use to determine the current
56         state of the fixed, moving, and other parameters of the parent gui.
57         """
58         self.registrationState = registrationState
59         if not self.parent:
60             self.parent = slicer.qMRMLWidget()
61             self.parent.setLayout(qt.QVBoxLayout())
62             self.parent.setMRMLScene(slicer.mrmlScene)
63             self.parent.show()
64             self.frame = qt.QFrame(self.parent)
65             self.frame.setObjectName("EditOptionsFrame")
66             self.frame.setLayout(qt.QVBoxLayout())
67             self.parent.layout().addWidget(self.frame)
68             self.widgets.append(self.frame)
69
70     def destroy(self):
71         """Call this method from your subclass to manage dynamic layout
72         and widget deleting"""
73         for w in self.widgets:
74             self.parent.layout().removeWidget(w)
75             w.deleteLater()
76             w.setParent(None)
77         self.widgets = []
78
79     def onLandmarkMoved(self, state):
80         """Called when the user changes a landmark"""
81         print(state)
82         pass
```

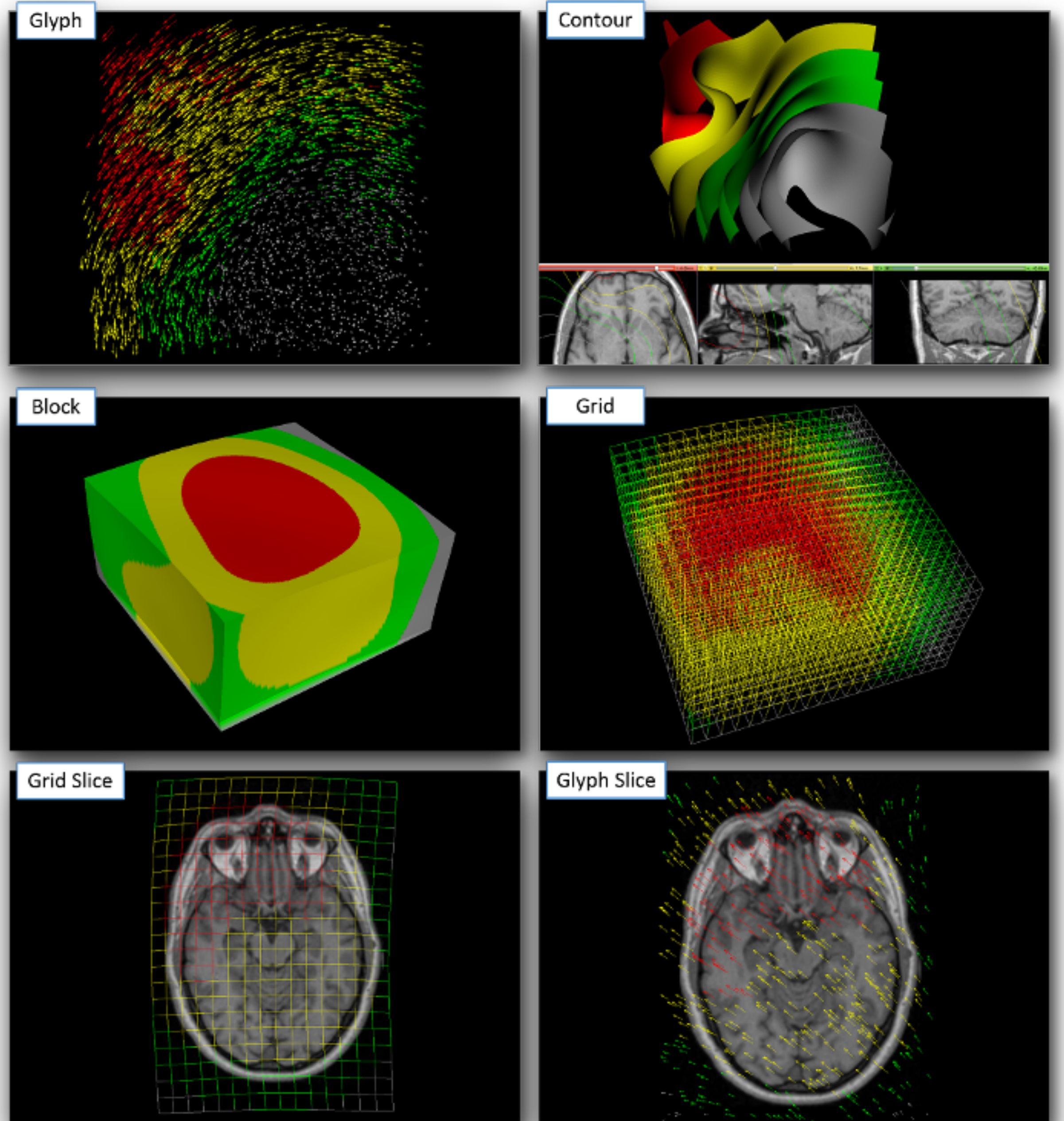




# Visualization

- Transform Visualizer
  - Creates Models of Transforms
  - Support Linear and Nonlinear Transforms
  - User Control of Sampling/Display
  - Integrates with Other Slicer Visualization
  - Look at the Transformation Instead of the Effect of the Transformation
- Bundled with SlicerRT Extension

Work in Progress





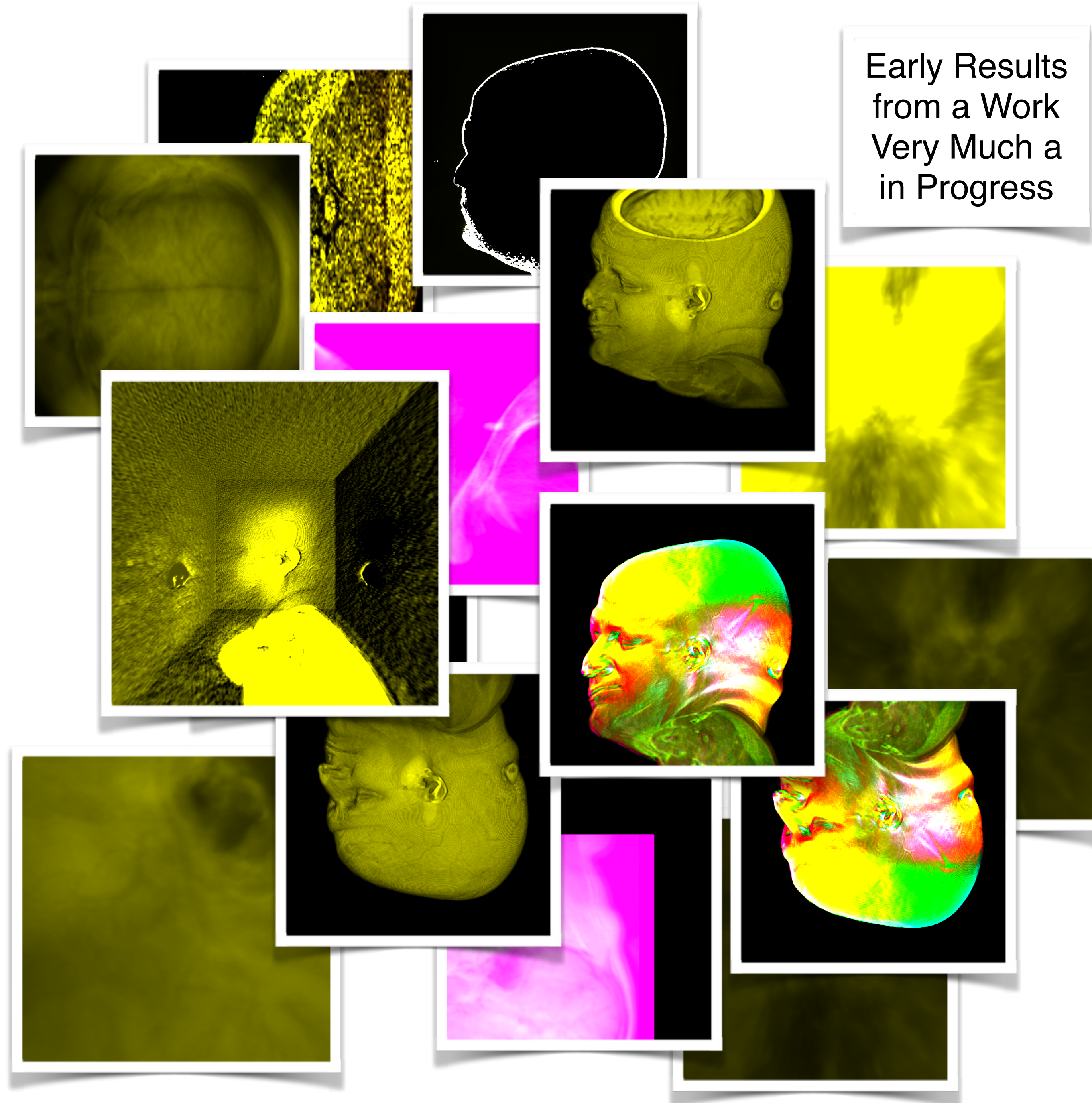
# Visualization

- OpenCL Volume Rendering

- Pixel-Parallel Ray Casting from Scratch
- Hardware Trilinear Interpolation
  - Volumes, Transfer Functions, Vector Fields
- PyOpenCL Integration with Slicer
- Custom Render Kernels

- TODO

- Coordinate Integration
- Multiple Volumes
- Linear and Nonlinear Transforms
- Integration with Surface Rendering
- Lighting/Shading Models
- Cutaway Rendering



Early Results  
from a Work  
Very Much a  
in Progress



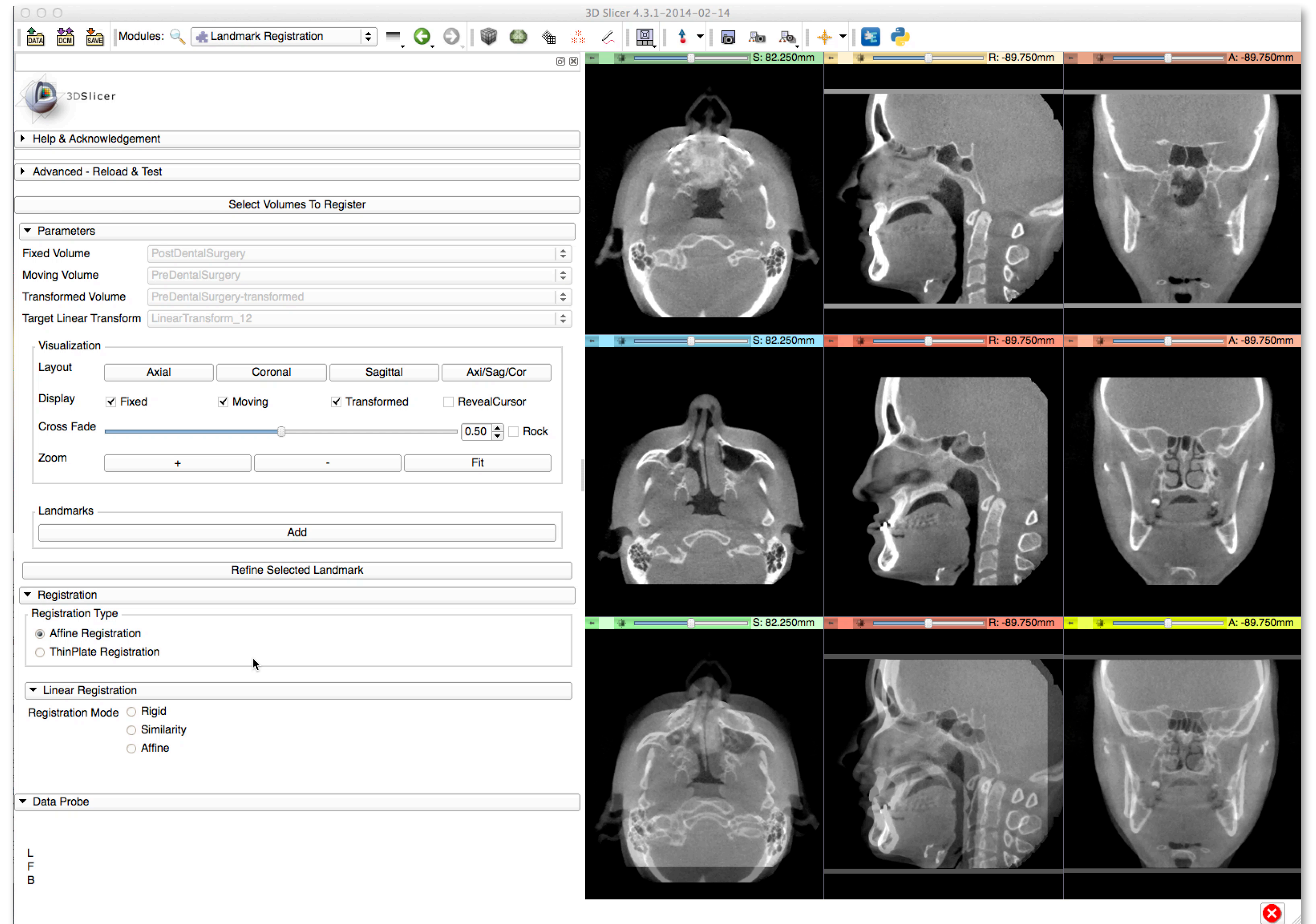
# Visualization/Control: Landmarks

## Manage Fiducials

- Auto Create Matching Fiducials
- Only Display on Proper Volume
- Fiducial-Centered View Options
- Arguably Allows Principled Control in 2D and 3D
- Grab in Fixed or Moving, but watch Blended...

## Based on Current Slicer

- Earlier Version in Nightly
- Improved Version Soon
- Needs Robustness, Documentation





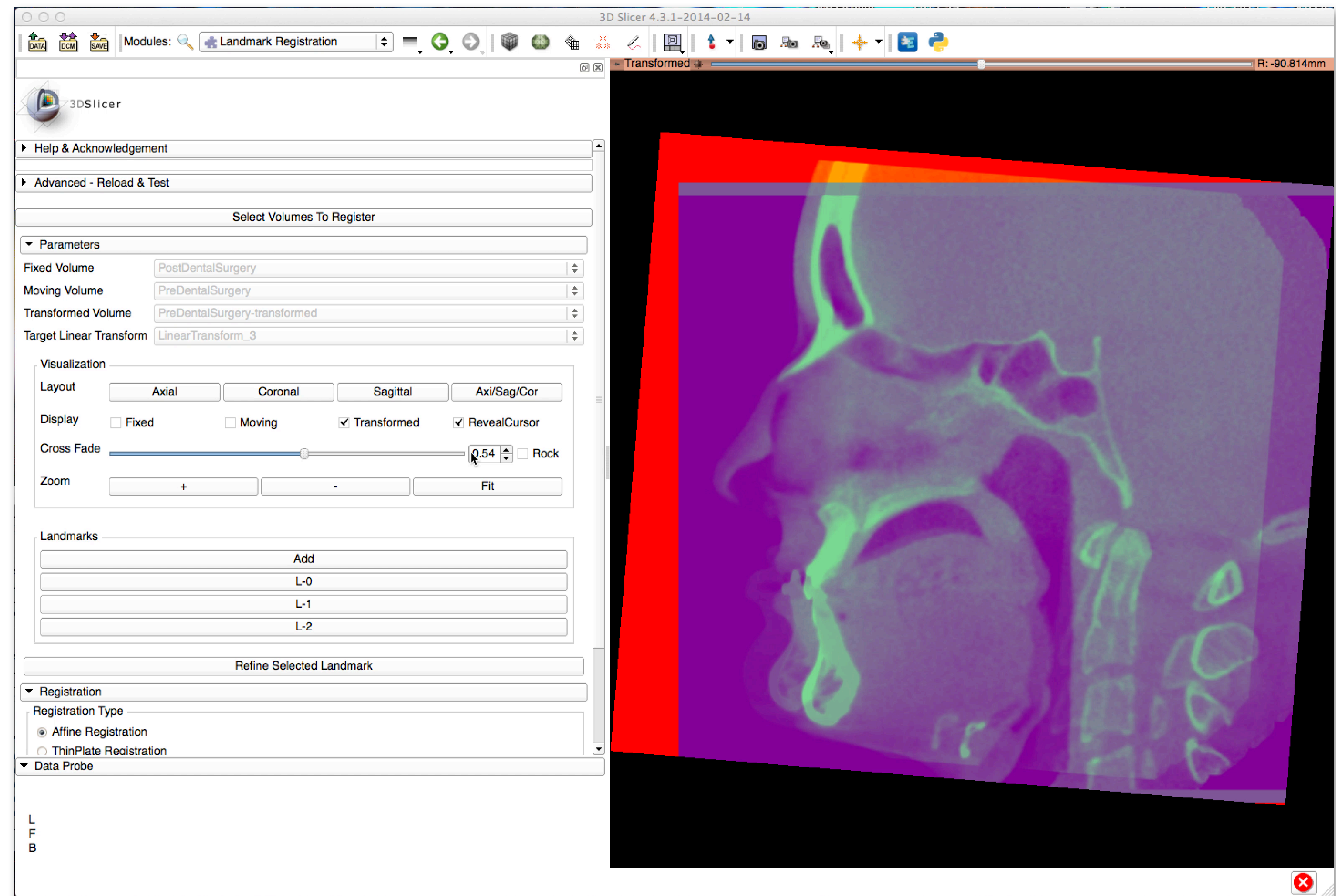
# Visualization: Rock and Reveal

## ● Rock

- Visualization Mode Implemented First by Patient who Used Slicer to Educate Surgeons about his Case
- Passive Contemplation of the Registration
- Other Color/Animation Modes Planned

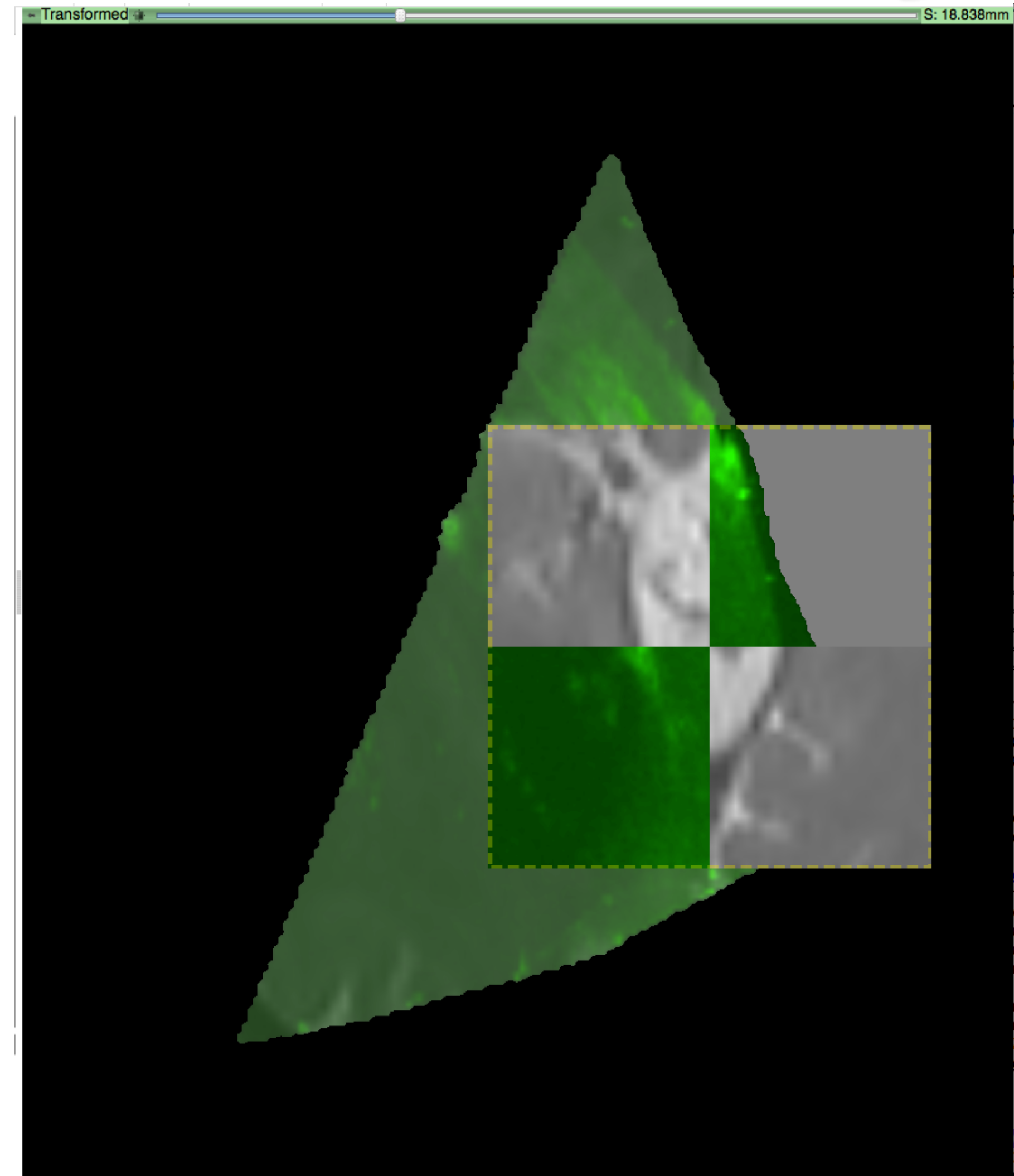
## ● Reveal Cursor

- Active Exploration and Comparison
- Facilitates Visualization of Discontinuities



# Visualization

- **Reveal Cursor**
  - Highly interactive visual inspection
  - Checkerboard of FG/BG layers
  - Optional zoom
  - Integrates nicely with pan/zoom/scroll/crosshairs
  - Integrated with LandmarkRegistration
- **Supports QC of Registration Results**



US (green) and T1 MR (gray) for AMIGO neurosurgery case



# 3D Control

- VTK Widgets

- Traditional Mouse/Keyboard Interaction
- Two DOFs

- Multitouch Screens

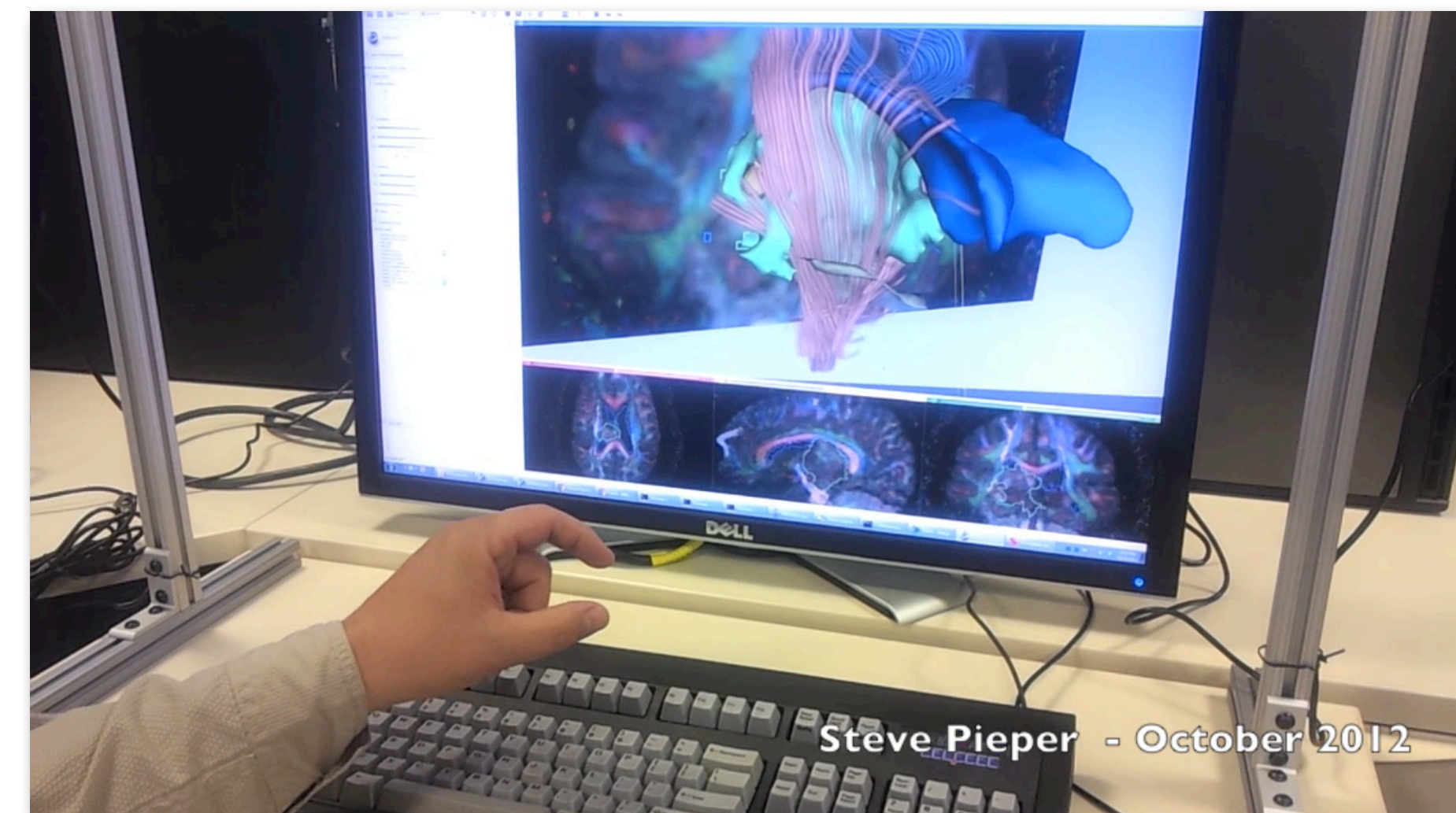
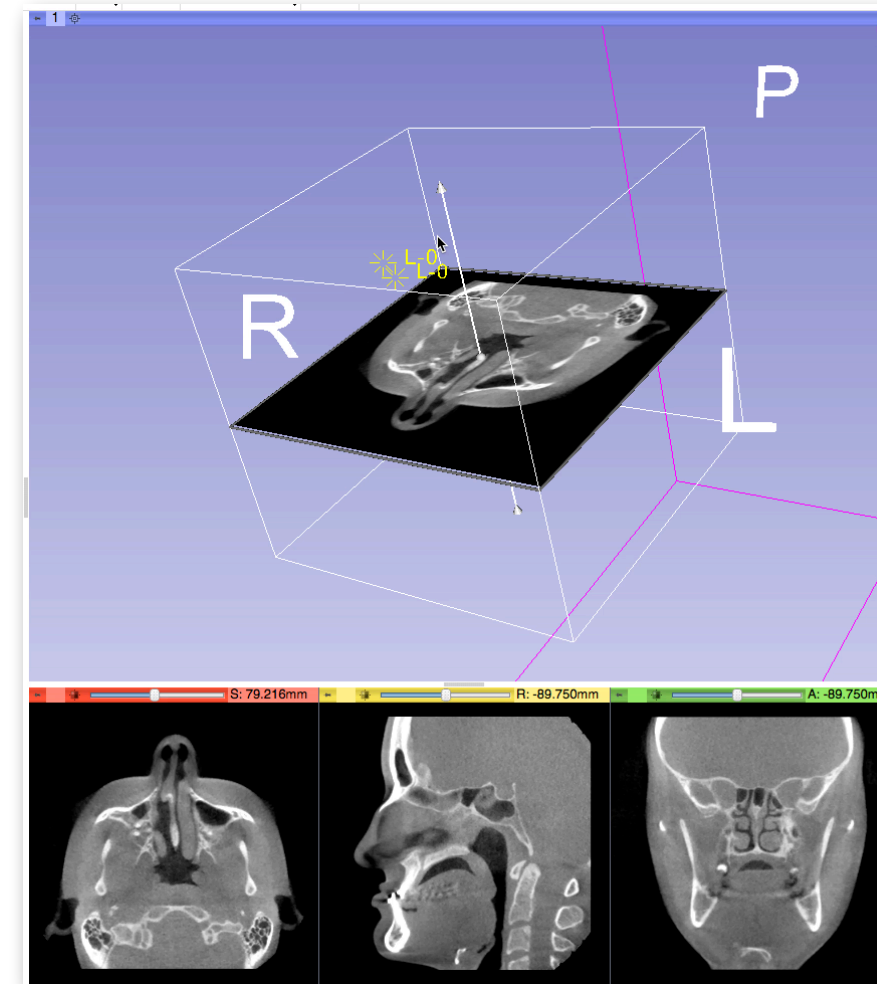
- iPad in AMIGO
- Three or More Simultaneous DOFs

- Hand Tracking

- ThreeGear Kinect/PrimeSense, Leap, Structure Sensor
- Twelve+ DOF? 72 DOFs?

- Visualization/Control

- ZSpace “Virtual Holography”
- Head Tracked Stereo Display
- Haptic Stylus
- Partial Slicer Integration



Works in Progress



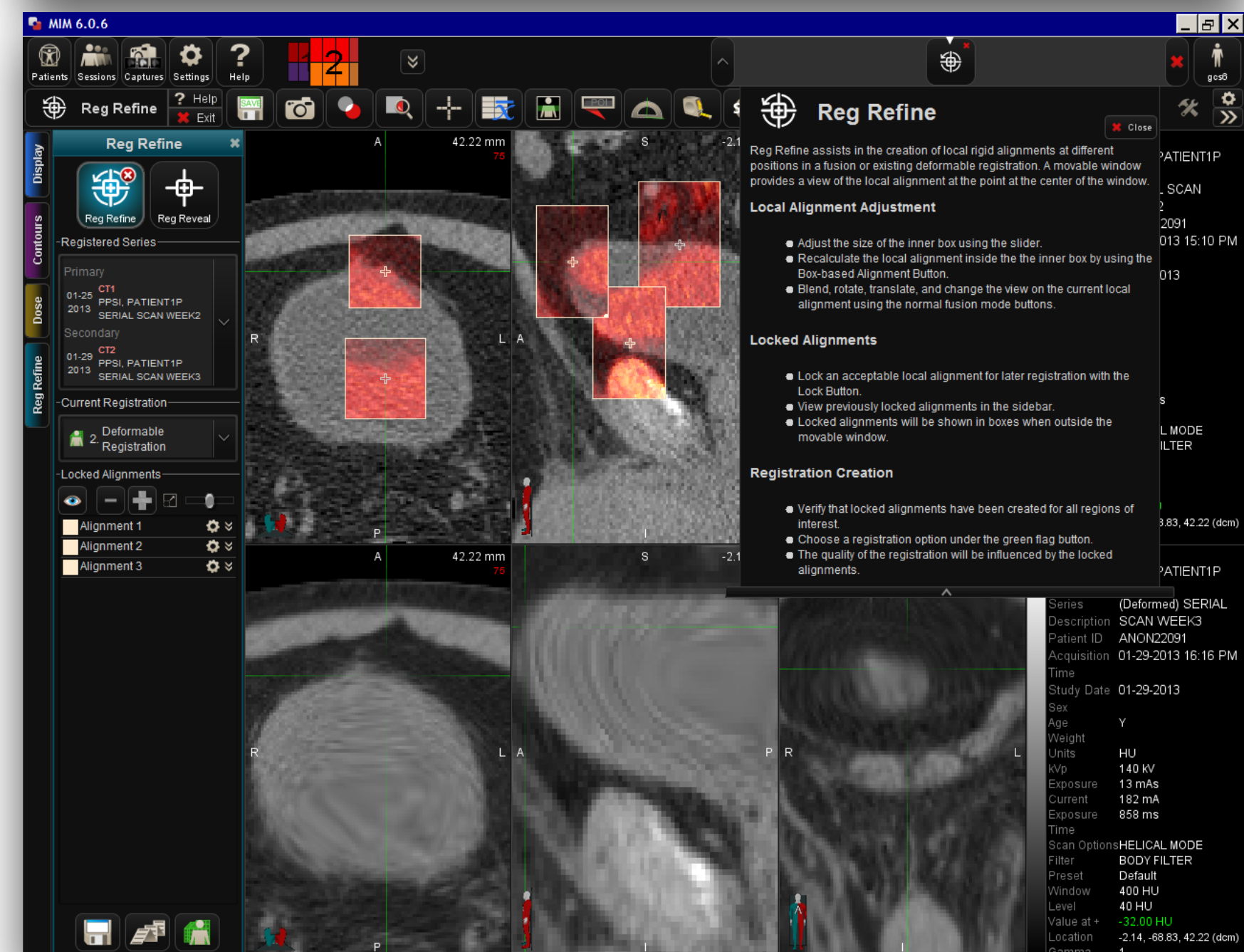
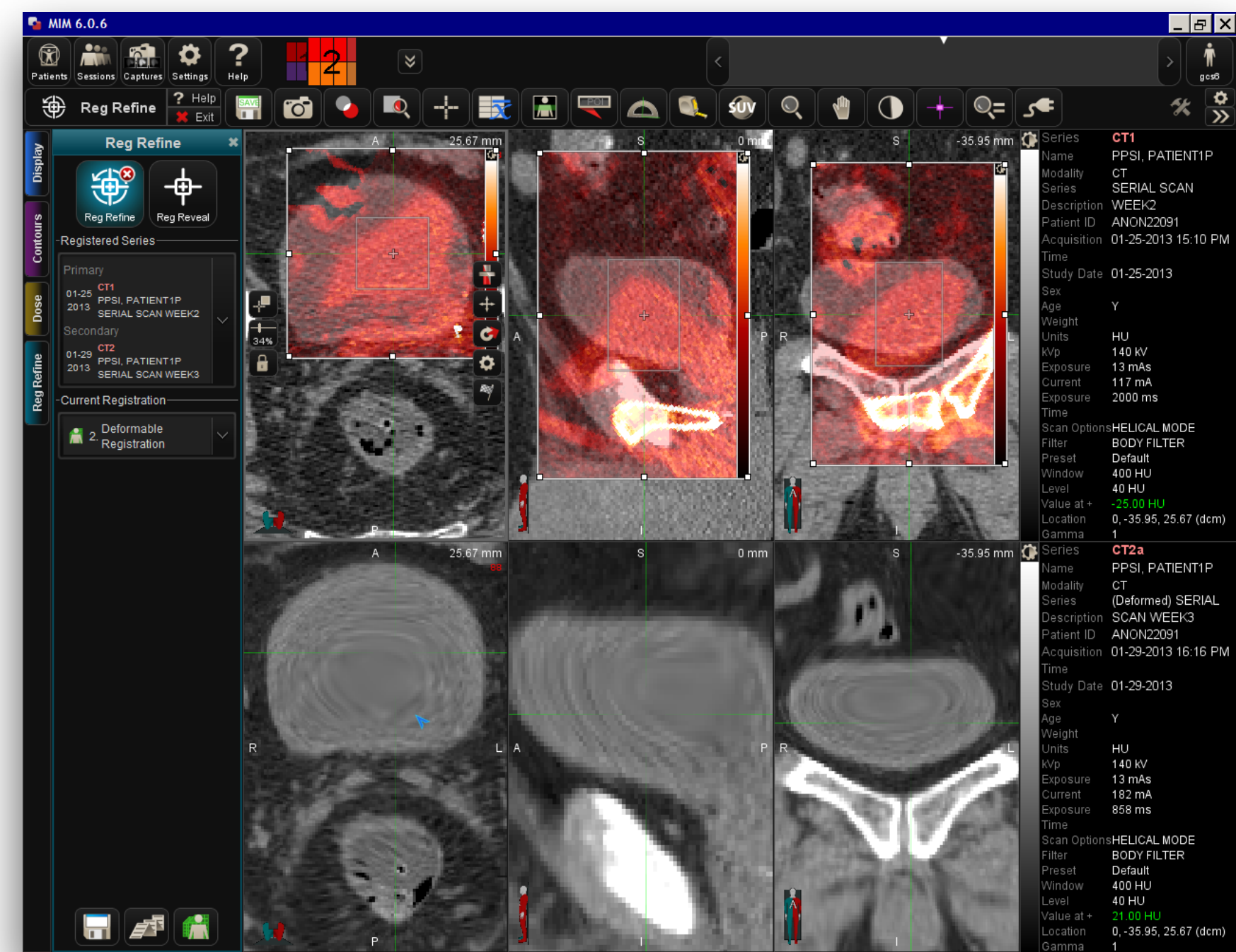
# Control/Automation

- MIM RegRefine

- Commercial Example of Registration Steering
- User Provides Local Correspondence
- Can be Fully Manual or Automatic within ROI

- WIP in Slicer LandmarkRegistration

- Extract ROI Around Fixed and Moving Fiducials
- Run BRAINSFit CLI on Extracted Volumes
- Update Fiducial Location
- Miller, Prastawa, Pieper



# Control/Automation

- Hybrid BSpline
  - Initialize from Landmarks
  - Include Landmark and Image Similarity Terms in Optimization
  - Support Iterative Refinement
- Part of Plastimatch
  - LandmarkRegistration Plugin
  - Bundled with SlicerRT Extension
  - MGH: Sharp, Shusharina



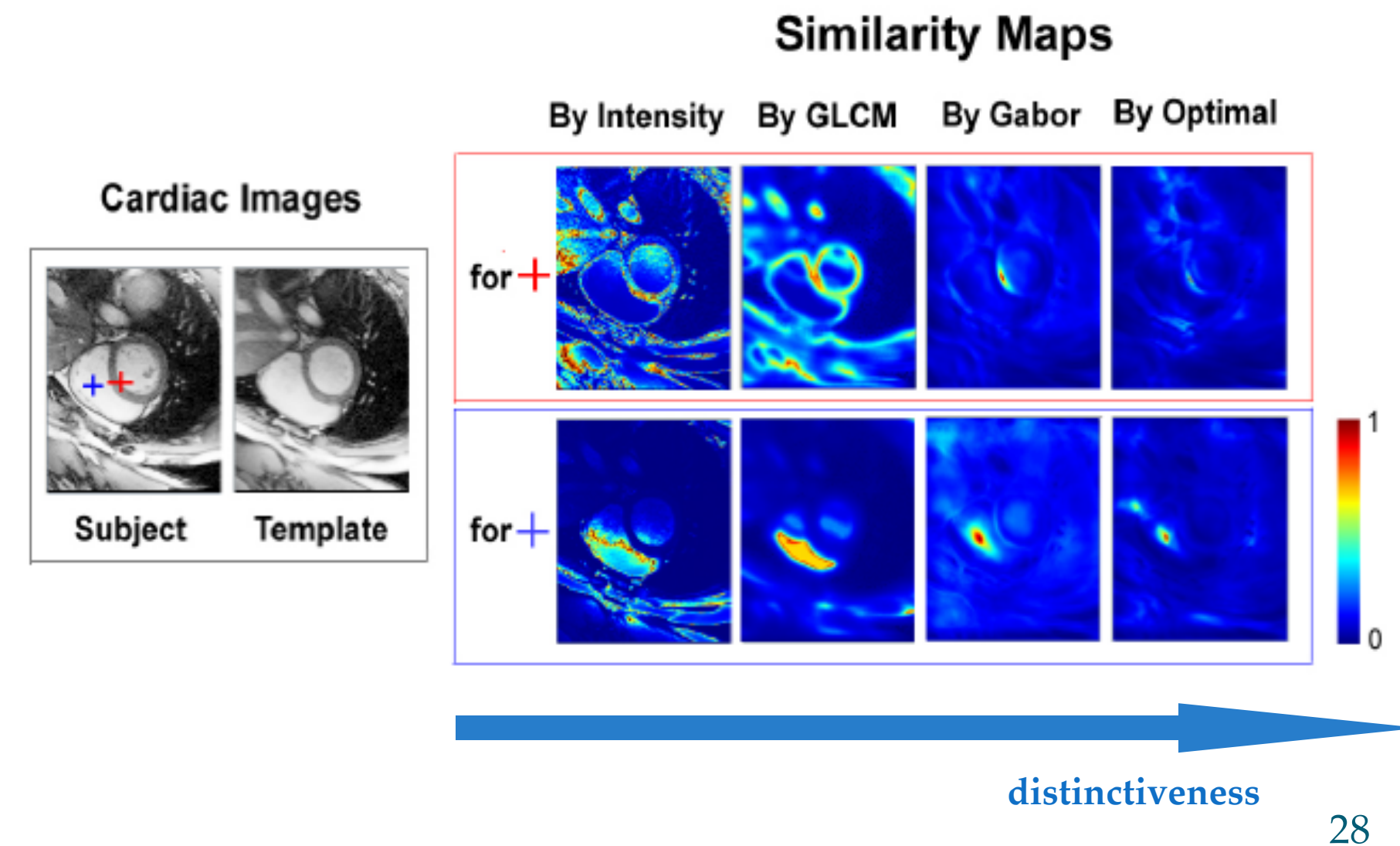
# Automation

- Marcel's GPU fluid registration

# Automation

- ◎ Yangming Ou DRAMMS
  - Deformable Registration by **Attribute Matching** and **Mutual Saliency**
  - PhD with Christos Davitzikos at UPenn
  - Now Post Doc with Randy Gollub and Jayashree Kalpathy at MGH
  - Working on mi2b2 and QIICR Projects
  - Wrapping DRAMMS as CLI Extension
- ◎ Exploring Approaches to Weight Attribute Match Criteria Based on User Input
  - Train Weighting from Landmarks

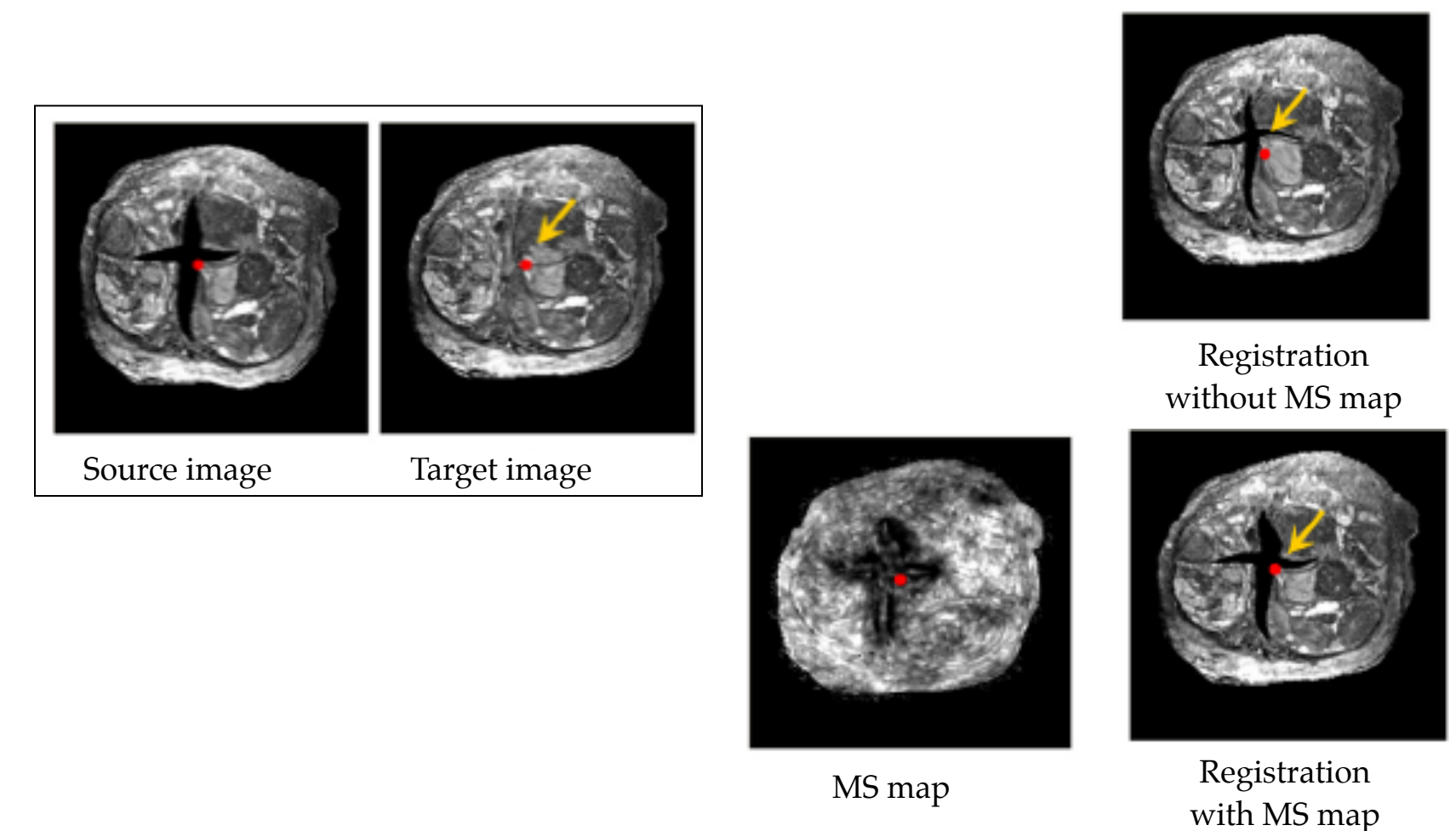
## 3.2. Role of Gabor Attributes and Optimal Gabor Attributes



## Part 3. DRAMMS: Algorithm

## 3.3. Role of Mutual-Saliency Map

- Account for partial loss of correspondence

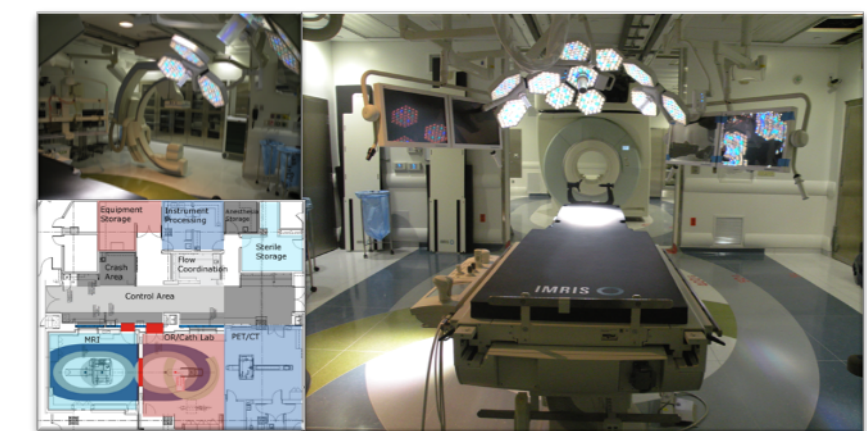
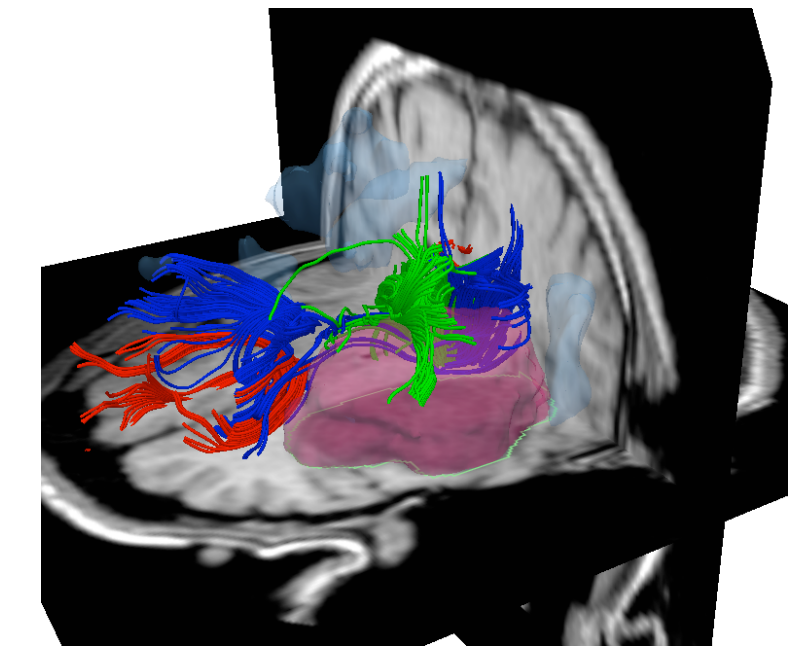
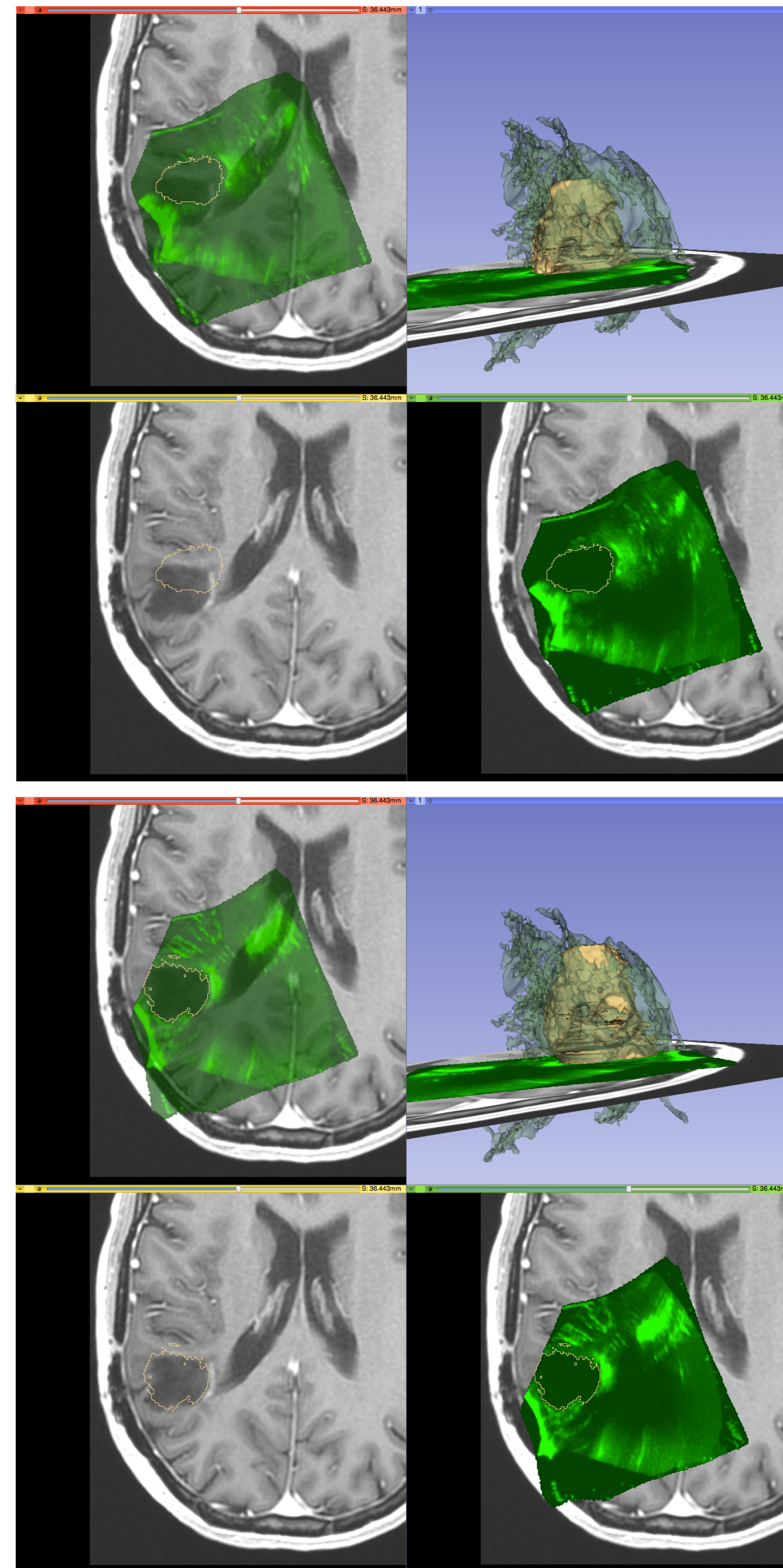


Why do this anyway?



# NAC / NCIGT

- Neurosurgery in AMIGO is DBP for current cycle of NAC (currently in year 1 of 5)
  - Improve the utility of iterated intra-procedural multi-modality imaging
    - Correct for calibration issues, distortion, resection, swelling...
    - Provide information in a clinically useful timeframe
  - Collect data during procedure: CaseHub
    - Multitrack recording of image data (video, ultrasound, vital monitors, navigation screen, MR console...)
    - Provide context for interpretation
- Active Participants
  - BWH: Golby, Norton, Mehrtash, Kikinis
  - GE: Miller, Prestawa
  - Isomics: Pieper, Blezek
- Registration Issues
  - MR/MR, MR/US, Video, Surface Scan
  - Warps, Brain Shift, Resection, Adema, Non-tissue, Lost Calibraion...





# QIICR



- Quantitative Image Informatics for Cancer Research (currently in year 1 of 5)

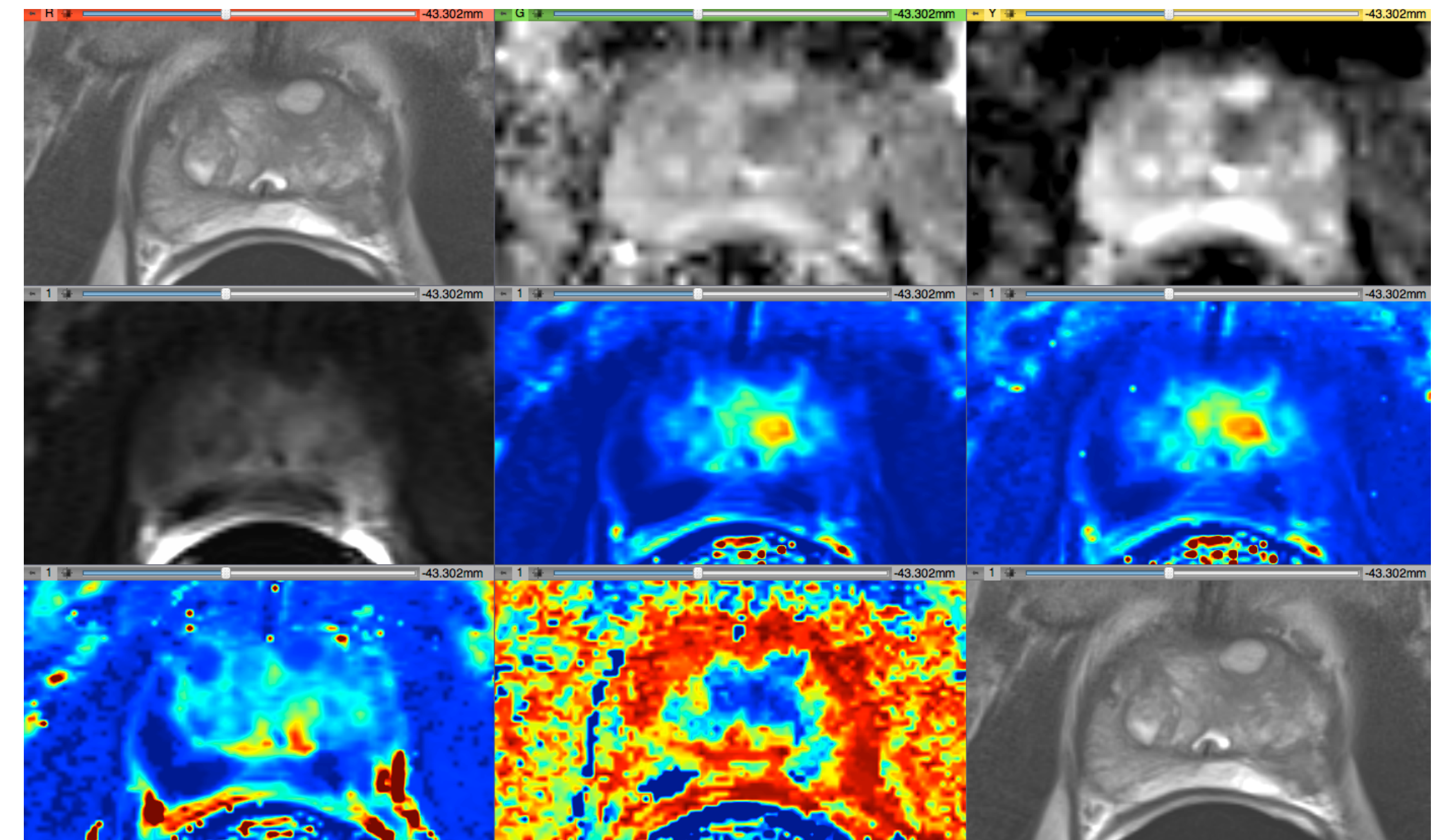
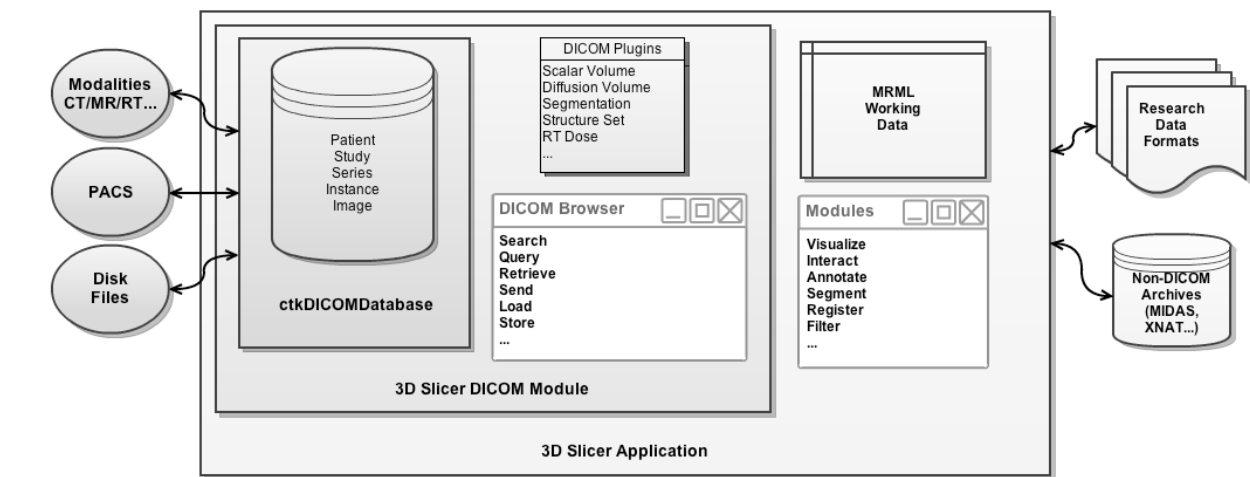
- NCI U24, Quantitative Imaging Network

- Active Participants

- BWH Prostate: Fennessy, Fedorov, Kikinis
- MGH GBM: Kalpathy, Ou
- Iowa HNC: Beichel
- Isomics: Pieper
- PixelMed: Clunie
- Open Connections: Onken

- Registration Issues

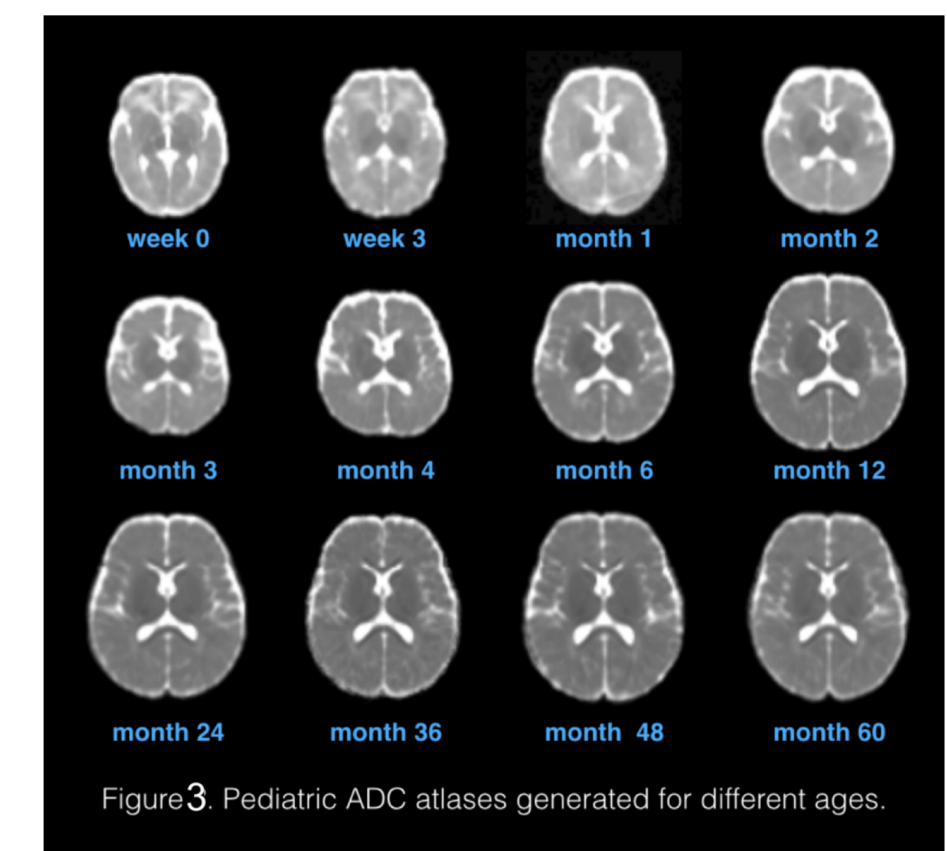
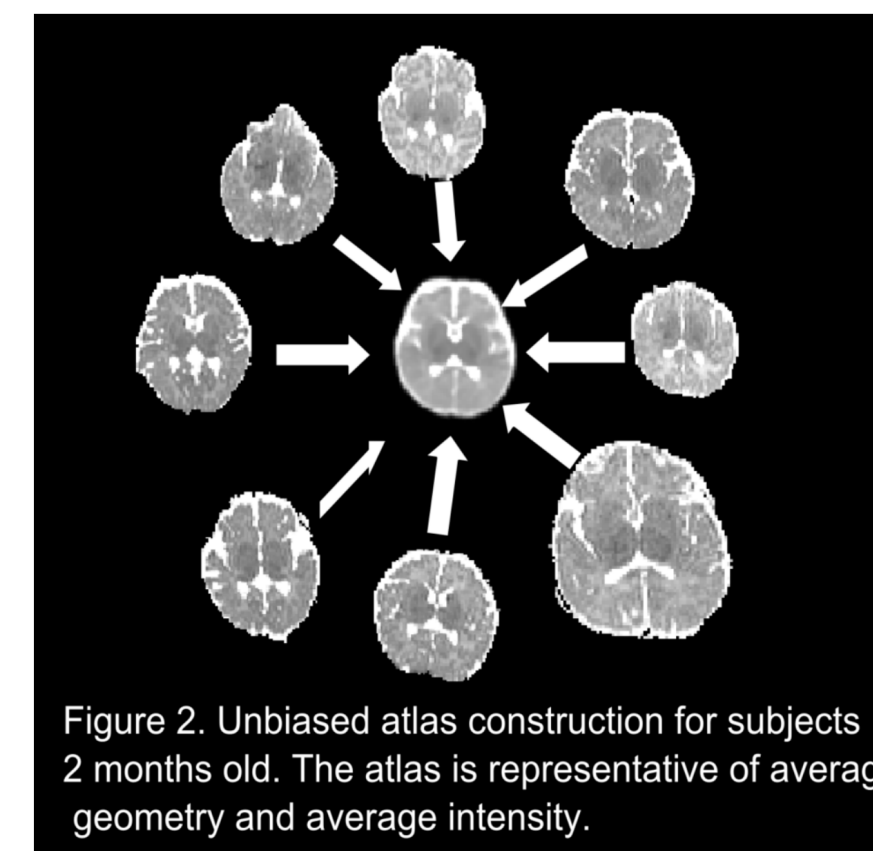
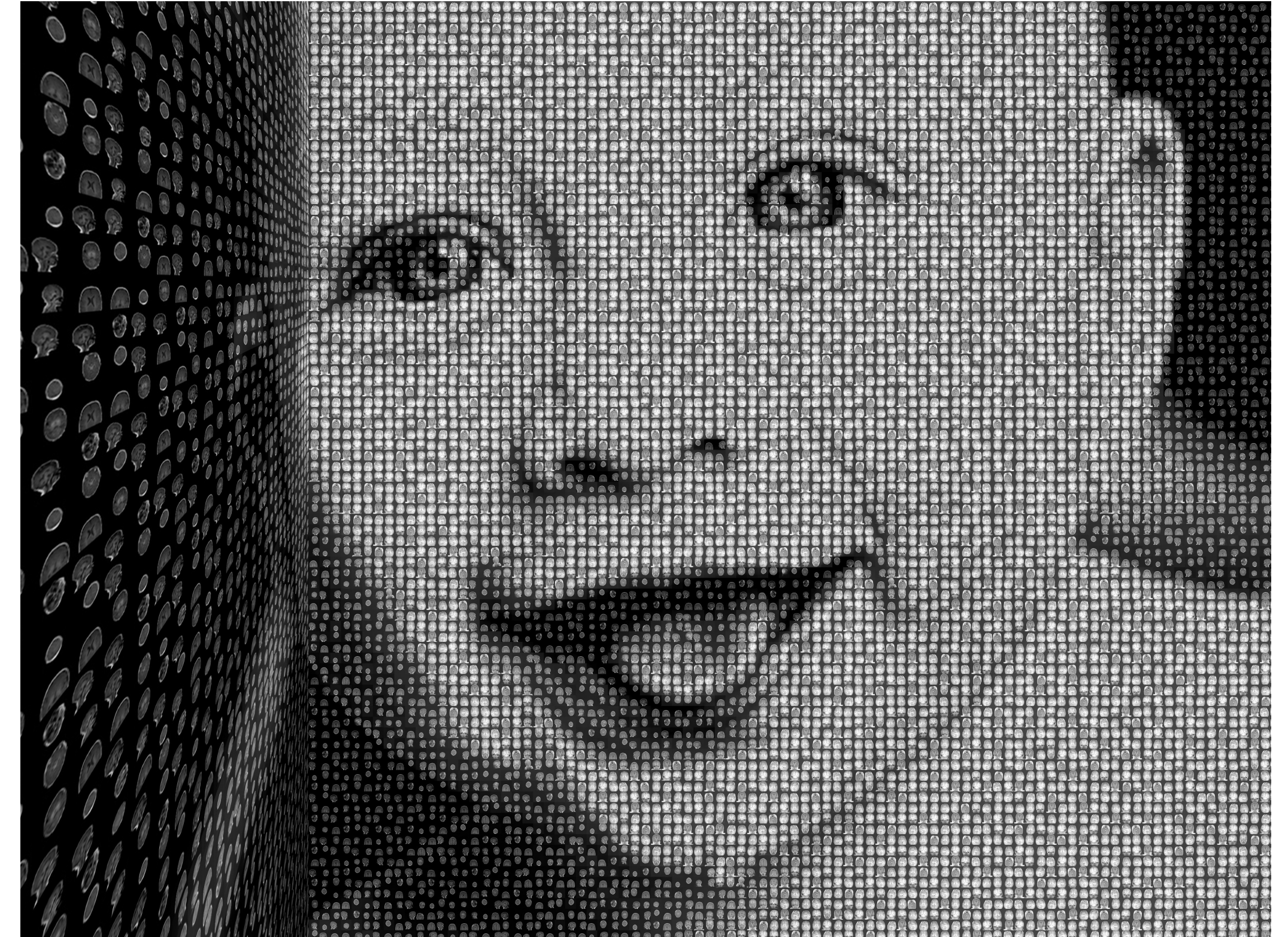
- Longitudinal Tumor Tracking
- mpMR, PET/CT





# mi2b2

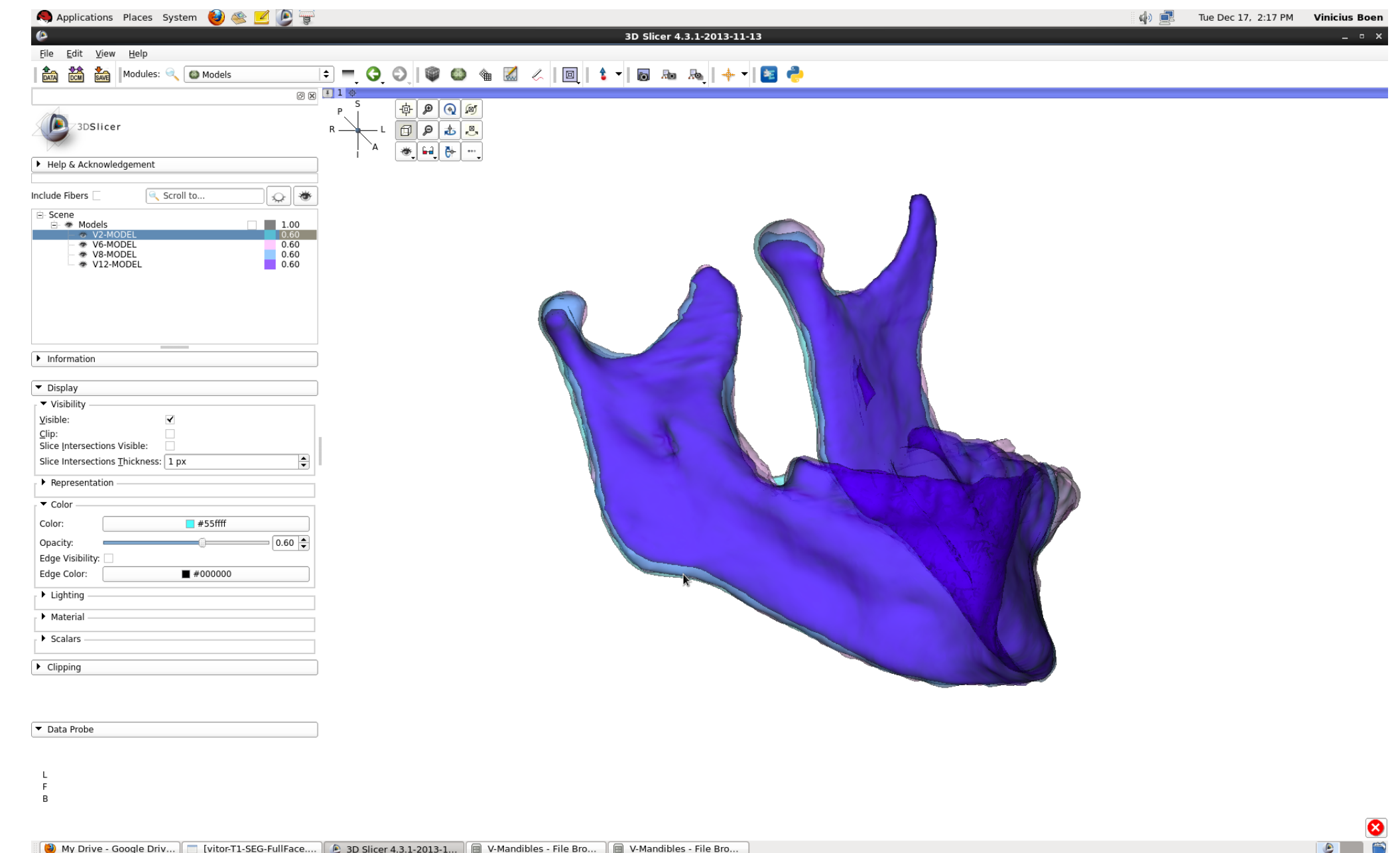
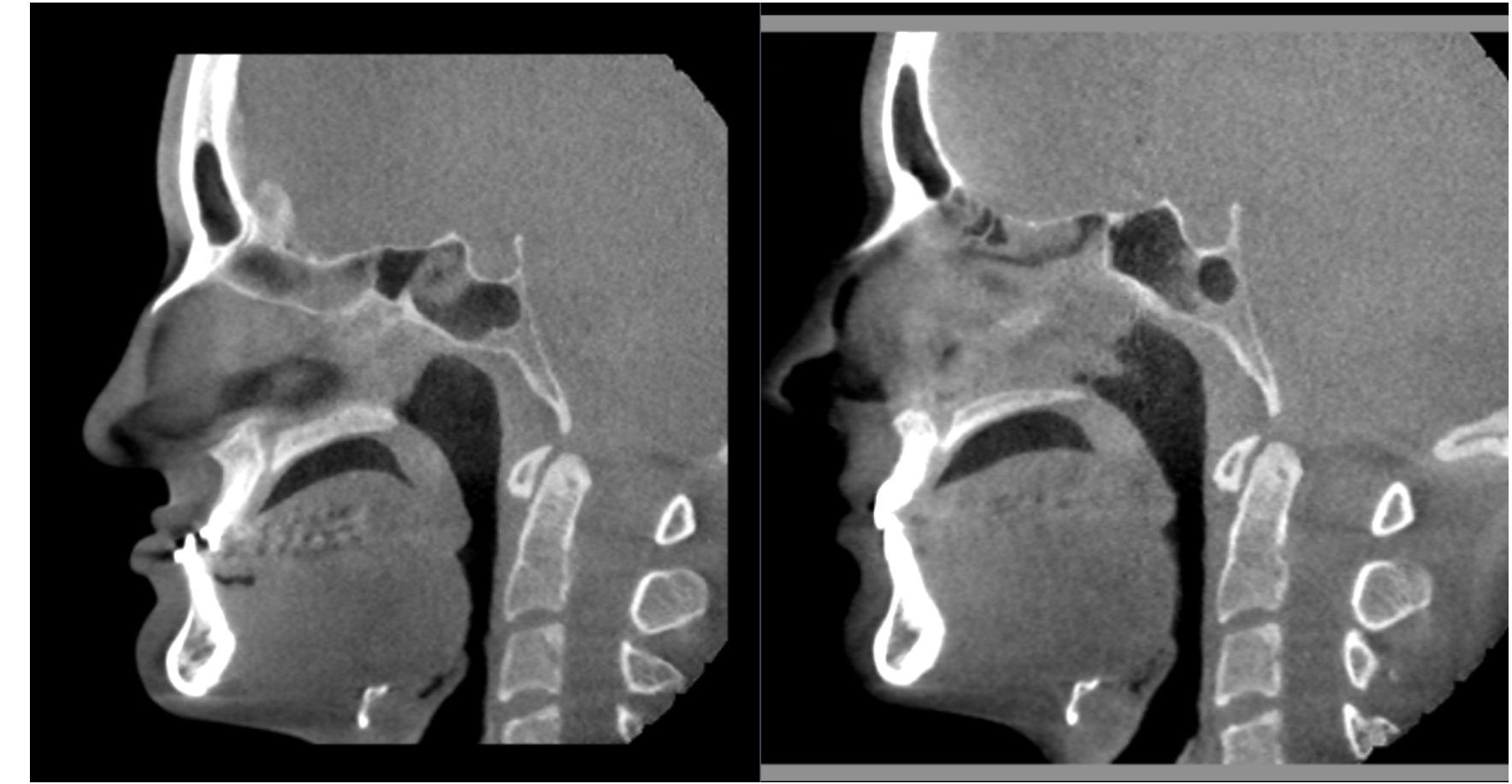
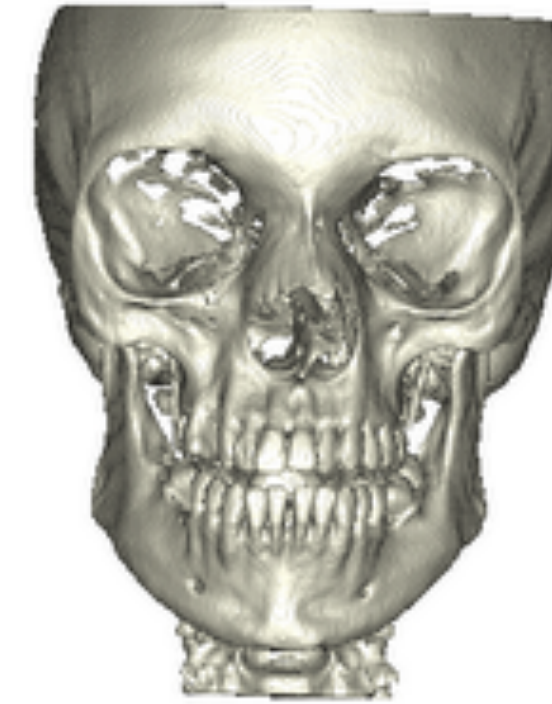
- Medical Image Informatics Bench to Bedside (currently in year 2 of 4)
  - NIBIB R01
  - Mine the Clinical PACS and EHR
  - Application to Pediatric Neurodevelopment
- Active Participants
  - MGH: Murphy, Gollub, Zollei, Herrick, Ou...
  - Childrens: Grant, Pienaar, Haehn...
  - Isomics: Pieper
- Registration Issues
  - Intersubject Atlas
  - Clinical Image Quality





# TMJ-OA

- Osteoarthritis of the Temporomandibular Joint (currently in year 1 of 4)
  - NIDCR/NIBIB R01
  - Before and After Craniomaxillofacial Surgery
  - Longitudinal Cone Beam CT to Track Atrophy
- Active Participants
  - Michigan: Cevedanes, Boen
  - UNC: Styner, Paniagua, Nguyen
  - Isomics: Pieper
- Registration Issues
  - Longitudinal CBCT
  - Atrophy, Surgical Intervention, Implant Artifacts
  - Quantifying Shape Change

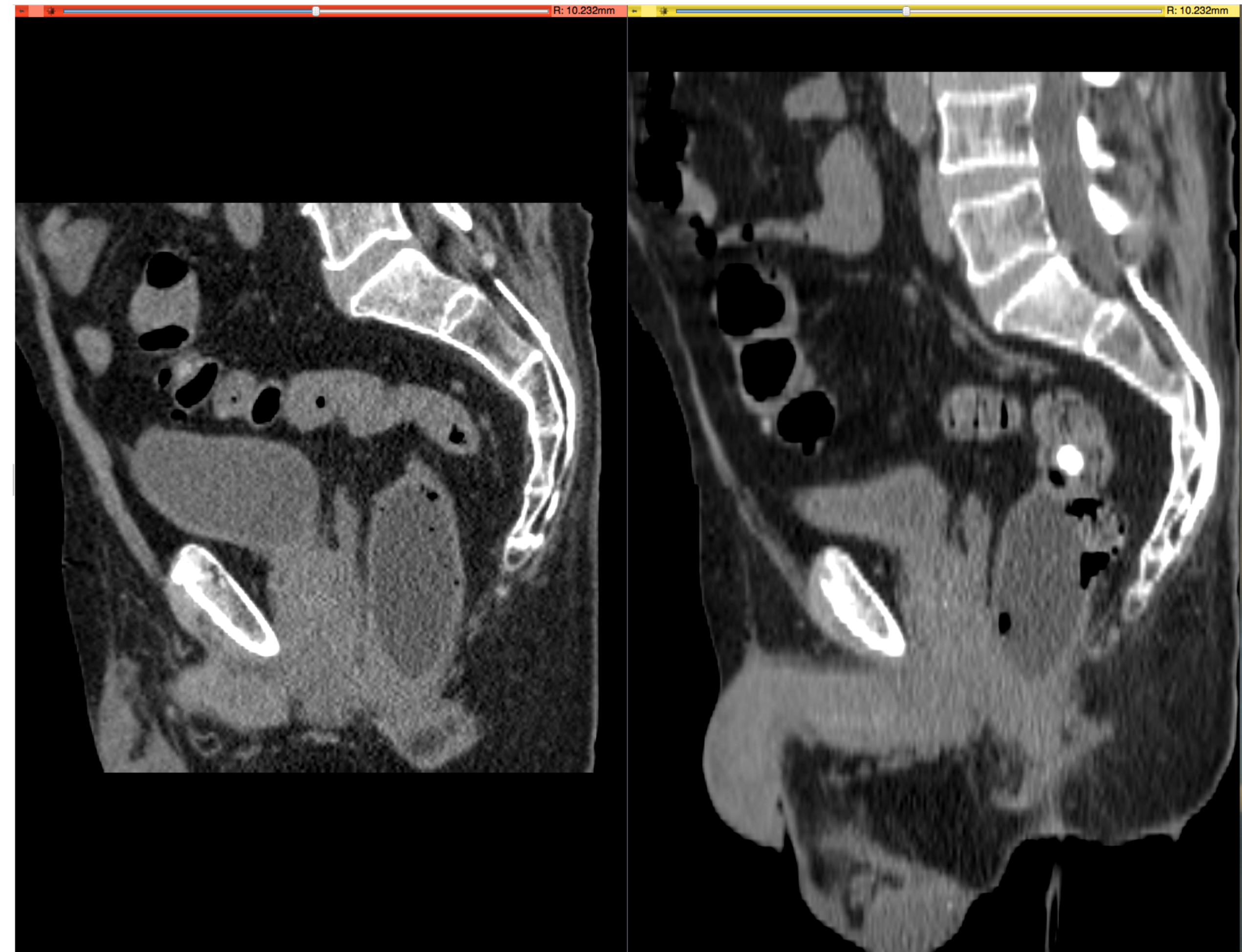




# NA-MIC

Plastimatch

- National Alliance for Medical Image Computing (currently in year 10 of 10)
  - NIH U54
  - Develop National Software Infrastructure for Medical Image Computing
  - DBP in Head and Neck Cancer Adaptive Proton Radiotherapy
- Active Participants in DBP
  - BWH: Kikinis
  - MGH: Sharp, Shusharina
  - GE: Miller, Prastawa
  - Isomics: Pieper, Yarmarkovich
- Registration Issues
  - CT/MR, CT/CBCT
  - Pose, Therapy Response, Physiology





# Discussion Topics

- ◉ Algorithms for Steering Automation
  - MI? SIFT? Others?
- ◉ Other Precedents
  - Commercial? Academic? Daydreams?
- ◉ Live Demos
  - I have many datasets and prototypes with me
- ◉ Other Ideas?
  - ?